

3.9 Moments and Moment-Generating Functions

Defn: The k -th moment about the origin of a r.v. Y (also simply called the k -th moment of Y) is defined as:

Examples of moments:

- The first moment, μ'_1 , is the _____ of Y .
- We know $\mu'_2 - [\mu'_1]^2$ is the _____ of Y .
- The third moment μ'_3 is related to the skewness (lack of symmetry) of a distribution.
- The fourth moment μ'_4 is related to the kurtosis (peakedness) of a distribution.

Note: The expression $E[(Y-\mu)^k]$ is sometimes called the k-th moment about the mean (or k-th central moment) of Y and is denoted by μ_k .

Defn (Moment-generating function):

The moment-generating function (or mgf) of a r.v. Y is denoted by $m_Y(t)$ and defined to be:

- The mgf for Y exists if there exists some $b > 0$ such that

- If $E[e^{tY}]$ does not exist in any open neighborhood around $t=0$, then $m_Y(t)$ does not exist.

- If the mgf exists, it characterizes all the moments of Y ,
 $E(Y^k), k=1, 2, 3, \dots$

Theorem: If $m_y(t)$ exists, then for any integer $k \geq 1$,

Examples: To get the first moment $E(Y)$, take the derivative (with respect to t) $m_y'(t)$ and plug in $t=0$.

- To get the second moment $E(Y^2)$, take the 2nd derivative $m_y''(t)$ and plug in $t=0$.

- To prove the theorem, recall:

The Maclaurin series expansion of an infinitely differentiable function $f(y)$ is given by:

-We can easily verify that the Maclaurin series expansion of $f(y) = e^{ty}$ is:

So $m_y(t) =$

So plugging in $t=0$,

- This proof requires interchanging derivatives and infinite sums, which is justified if $m_Y(t)$ exists.

Example 1: (Recalls Petersburg paradox):

Let a r.v. Y have probability function

$$p(y) = \left(\frac{1}{2}\right)^y \quad \text{for } y=1, 2, 3, \dots$$

Find $m_Y(t)$ and then $E(Y)$.

Example 2: Let Y have probability function

$$p(y) = \frac{y}{10} \quad \text{for } y = 1, 2, 3, 4.$$

Find $m_Y(t)$ and $E(Y)$.

- For Example 2, it is easier to find $E(Y)$ directly using the definition.

Example 3 (Variance of a Poisson r.v.):

Let $Y \sim \text{Pois}(\lambda)$ with probability function

$$p(y) = \frac{\lambda^y}{y!} e^{-\lambda} \quad \text{for } y = 0, 1, 2, \dots$$

Find the mgf and variance of Y .

Lemma: For any number x ,

Thus

Then

We have proved that $E(Y) = \lambda$ for
 $Y \sim \text{Pois}(\lambda)$, so

Example 4: The mean and variance of a $\text{Bin}(n, p)$ r.v. can also be found using the binomial mgf:

which may be derived by considering the binomial expansion of $(pe^t + q)^n$.

Example 5: (Mean and variance of a negative binomial r.v.):

Let $Y \sim \text{NB}(r, p)$. Find $m_Y(t)$, $E(Y)$, and $V(Y)$.

Lemma: For any integer $r \geq 1$,

Proof:

Hence

Letting $x =$ and $j =$ yields the lemma.

$$\text{Now } m_Y(t) = E[e^{tY}] =$$

To get the variance, after much tedious calculus:

Corollary (Geometric variance):

If $Y \sim \text{geom}(p)$, then $V(Y) =$

- An important fact is that a mgf completely characterizes a probability distribution.
- If $m_Y(t)$ exists for distribution $p(y)$, then it is the unique mgf for Y .

- If two r.v.'s have the same mgf, then they must have the same distribution.

- So we can often use the mgf to identify the distribution of a r.v.

Example 6: If Y is a r.v. with mgf $m_Y(t) = e^{7.1e^t - 7.1}$, then what is the distribution of Y ?

Example 7: If Y has mgf

$m_Y(t) = \frac{e^t}{2 - e^t}$, then what is the distribution of Y ?