

# STAT 530/J530 September 22<sup>nd</sup>, 2005

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## Principal Components

$$Y = a_1 X_1 + a_2 X_2 + \dots + a_q X_q$$

or

$$Y_{(n \times q)} = X_{(n \times q)} A_{(q \times q)}$$



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## Reversing It

If we have Y we should be able to get X... say using regression.

In fact in this case we should get it exactly!

$$Y_{(n \times q)} A^{-1}_{(q \times q)} = X_{(n \times q)} A_{(q \times q)} A^{-1}_{(q \times q)}$$

$$X_{(n \times q)} = Y_{(n \times q)} A^{-1}_{(q \times q)}$$



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### Checking What Was Lost

```
sect3<-as.matrix(oildata[,12:31])  
  
a<-eigen(cov(sect3))$vectors  
y<-sect3%*%a  
  
summary(lm(sect3[,1]~y))$r.squared
```

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### What if we only kept 4 PC's?

```
y4<-y[,1:4]  
summary(lm(sect3[,1]~y4))$r.squared  
  
sect3est<-sect3  
for (i in 1:20){  
  sect3est[,i]<-  
    lm(sect3[,i]~y4)$fitted.values}
```

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### Lots of Lost Information!

```
s3var<-apply(sect3,2,var)  
  
s3varest<-apply(sect3est,2,var)  
  
cbind(s3var,s3varest)  
  
cor(sect3)[1:4,1:4]  
cor(sect3est)[1:4,1:4]
```

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### Factor Analysis

Factor Analysis models are designed to account for this missing data by adding an error term to the model. (Assuming the X have been set to have mean 0.)

$$X_1 = a_{11}F_1 + a_{12}F_2 + \dots + a_{1k}F_k + \varepsilon_1$$

$$X_2 = a_{21}F_1 + a_{22}F_2 + \dots + a_{2k}F_k + \varepsilon_2$$

⋮

$$X_q = a_{q1}F_1 + a_{q2}F_2 + \dots + a_{qk}F_k + \varepsilon_q$$



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### Factor Analysis

Factor Analysis models are designed to account for this missing data by adding an error term to the model. (Assuming the X have been standardized we can write):

$$X_1 = \lambda_{11}F_1 + \lambda_{12}F_2 + \dots + \lambda_{1k}F_k + u_1$$

$$X_2 = \lambda_{21}F_1 + \lambda_{22}F_2 + \dots + \lambda_{2k}F_k + u_2$$

⋮

$$X_q = \lambda_{q1}F_1 + \lambda_{q2}F_2 + \dots + \lambda_{qk}F_k + u_q$$



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### Assumptions

- The  $u_i$  are independent of each other and of the  $F_i$
- The  $F_i$  are independent of each other
- Usually set the  $F_i$  to have mean 0 and variance 1



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## The Variances

We have:

$$X_i = \lambda_{i1}F_1 + \lambda_{i2}F_2 + \dots + \lambda_{ik}F_k + u_i$$

What can we tell about the variances and covariances?



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## In Matrix Form

If we write

$$X_{qx1} = \Lambda_{q \times k} F_{k \times 1} + u_{qx1}$$

Then

$$\Sigma = \Lambda_{q \times k} \Lambda_{k \times q}^T + \text{cov}(u)$$



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## What's Next

- How does it work?
- Any restrictions on the data?
- How many factors?
- Rotating the data
- Interpreting the results
- Using the results
- Graphically displaying the findings



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