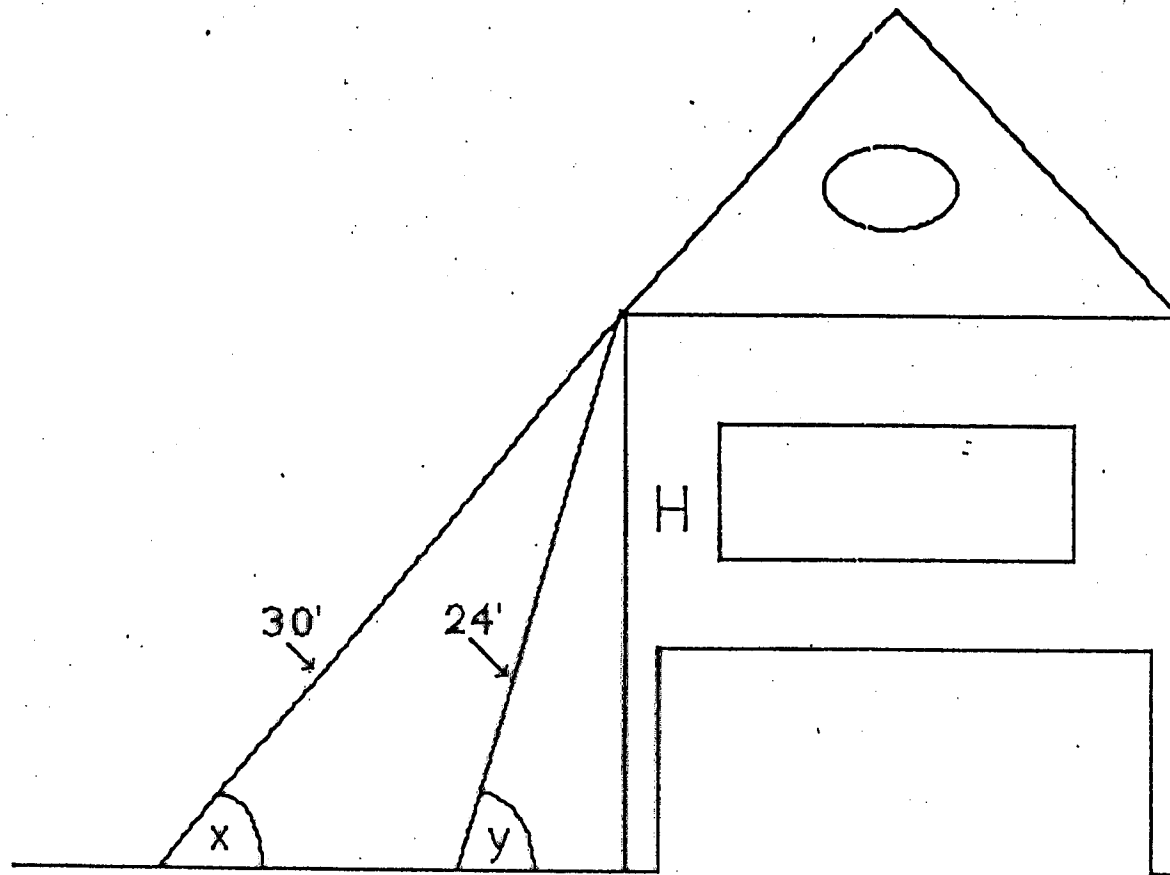


Estimate the angles 'x' and 'y'  
to the nearest degree



Estimates for  
angle 'x' \_\_\_\_\_ degrees  
angle 'y' \_\_\_\_\_ degrees

Name (initials only) \_\_\_\_\_