

1.1

Sample space:  $S$  = the set of all possible outcomes of an experiment

Countable if  $\exists$  a 1-1 correspondence w/ a subset of integers

Uncountable if  $\nexists$  a 1-1 correspondence (ie. real numbers)

Event: any collection of possible outcomes of an experiment, any subset of  $S$  which includes  $S$  itself

Containment  $A \subset B \iff x \in A \rightarrow x \in B$

Equality  $A = B \iff A \subset B \text{ \& } A \supset B$

Union:  $A \cup B = \{x \mid x \in A \text{ or } x \in B\}$

Intersection  $A \cap B = \{x \mid x \in A \text{ and } x \in B\}$

Complement  $A^c = \{x \mid x \notin A\}$

Null set  $\emptyset$  = the set consisting of no elements

Theorem  
1.1.4

a.  $A \cup B = B \cup A$

$$A \cap B = B \cap A$$

b.  $A \cup (B \cap C) = (A \cup B) \cap C$

$$A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$$

c.  $A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$

- Let  $x \in A \cup B$  then, by definition,  $x \in A$  or  $x \in B$ .  
then  $x \in B \cup A$  because  $x \in A$  or  $x \in B$  and def. of  $\cup$
- Let  $x \in A \cap B$  then, by definition,  $x \in A$  and  $x \in B$ .  
then  $x \in B \cap A$  because  $x \in A$  and  $x \in B$  and def. of  $\cap$
- Let  $x \in A \cup (B \cap C)$  then  $x \in A$  or  $x \in B \cap C$  which  
is the same as  $x \in A$  or  $x \in B$  or  $x \in C$  by def  $\cup$ .  
Let  $x_2 \in (A \cup B) \cap C$  then  $x_2 \in A \cup B$  or  $x_2 \in C$  which  
is the same as  $x_2 \in A$  or  $x_2 \in B$  or  $x_2 \in C$  by def  $\cup$ .  
 $\therefore A \cup (B \cap C) = (A \cup B) \cap C$  b/c they are defined the  
same way.
- Let  $x_1 \in A \cap (B \cup C)$  then  $x_1 \in A$  and  $x_1 \in B \cup C$  which  
is the same as  $x_1 \in A$  and  $x_1 \in B$  and  $x_1 \in C$  by def  $\cap$ .  
Let  $x_2 \in (A \cap B) \cup (A \cap C)$  then  $x_2 \in (A \cap B) \cup (A \cap C)$  which  
is the same as  $x_2 \in A$  and  $x_2 \in B$  and  $x_2 \in C$  by def  $\cap$ .  
 $\therefore A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$  b/c they are defined  
the same way, thus containment is established
- Let  $x_1 \in A \cap (B \cup C)$  then  $x_1 \in A$  and  $x_1 \in B$  or  $x_1 \in C$ .  
Let  $x_2 \in (A \cap B) \cup (A \cap C)$  then  $x_2 \in A$  and  $x_2 \in B$  or  $x_2 \in A$  or  $x_2 \in C$   
which is the same as  $x_2 \in A$  and  $x_2 \in B$  or  $x_2 \in C$   
 $\therefore A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$  b/c they are defined  
the same way, thus containment is established

$$A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$$

- Let  $x_1 \in A \cup (B \cap C)$  then  $x_1 \in A$  or  $x_1 \in B$  and  $x_1 \in C$
- Let  $x_2 \in (A \cup B) \cap (A \cup C)$  then  $x_2 \in A$  or  $x_2 \in B$  and  $x_2 \in A$  or  $x_2 \in C$  which is the same as  $x_2 \in A$  or  $x_2 \in B$  and  $x_2 \in C$
- ∴  $A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$  because they are defined the same way thus containment is established

$$d. (A \cup B)^c = A^c \cap B^c$$

- Let  $x_1 \in (A \cup B)^c$  then  $x_1 \notin A \cup B$  which is the same as  $x_1 \notin A$  and  $x_1 \notin B$  which is equivalent to  $x_1 \in A^c$  and  $x_1 \in B^c$
- Let  $x_2 \in A^c \cap B^c$  then  $x_2 \in A^c$  and  $x_2 \in B^c$
- ∴  $(A \cup B)^c = A^c \cap B^c$  because they are defined the same way thus containment is established

$$(A \cap B)^c = A^c \cup B^c$$

- Let  $x_1 \in (A \cap B)^c$  then  $x_1 \notin A \cap B$  which is the same as  $x_1 \notin A$  or  $x_1 \notin B$  which implies  $x_1 \in A^c$  or  $x_1 \in B^c$
- Let  $x_2 \in A^c \cup B^c$  then  $x_2 \in A^c$  or  $x_2 \in B^c$
- ∴  $(A \cap B)^c = A^c \cup B^c$  because they are defined the same way thus containment is established

$$\bigcup_i A_i = \{x \mid x \in A_i \text{ for some } i\}$$

$$\bigcap_i A_i = \{x \mid x \in A_i \text{ for all } i\}$$

Disjoint or Mutually Exclusive: if  $A \cap B = \emptyset$

Pairwise Disjoint or Mutually Exclusive: if  $A_i \cap A_j = \emptyset \quad \forall i \neq j$

Partition if  $A_i \cap A_j = \emptyset \quad \forall i \neq j$  and  $\bigcup_i A_i = S$

$$\bullet B = \{B \cap A\} \cup \{B \cap A^c\}$$

**Proof**  $x \in B$  and  $x \in A$  or  $x \in B$  and  $A^c$   
 $\equiv x \in B$  and  $x \in S$  ∴  $x \in B$  //

$$\bullet A \cup B = A \cup \{B \cap A^c\}$$

**Proof**  $A \cup B = A \cup [(B \cap A) \cup (B \cap A^c)]$  (by the proof above)  
 $= A \cup B \cap A^c$  ( $A \cup (\text{subset of } A) = A$ )

1.2

Def 1.2.1  $\sigma$  algebra or Borel field follows these axioms

- 1)  $\emptyset \in \mathcal{B}$
- 2) If  $A \in \mathcal{B}$  then  $A^c \in \mathcal{B}$  (closed under complementation)
- 3) If  $A_1, A_2, \dots \in \mathcal{B}$  then  $\bigcup A_i \in \mathcal{B}$  (closed under countable unions)

Def 1.2.4 A probability function w/  $S = \text{samplespace}$   $\mathcal{B} = \sigma$  algebra domain =  $\mathcal{B} \Rightarrow$

Kolmogorov axioms

- (1)  $P(A) \geq 0 \forall A \in \mathcal{B}$
- (2)  $P(S) = 1$

Axiom of finite additivity  $\rightarrow$

- (3) If  $A_1, A_2, \dots \in \mathcal{B}$  are pairwise disjoint (if  $A_i \cap A_j = \emptyset \forall i \neq j$ ), then  $P(\bigcup A_i) = \sum P(A_i)$
- (3R) If  $A \in \mathcal{B} \text{ ; } B \in \mathcal{B}$  are disjoint then  $P(A \cup B) = P(A) + P(B)$

Theorem 1.2.6 Let  $S = \{s_1, s_2, \dots, s_n\}$  and let  $\mathcal{B}$  be any sigma algebra of subsets of  $S$ . Let  $p_1, p_2, \dots, p_n \geq 0 \Rightarrow \sum p_i = 1$ . Then  $\forall A \in \mathcal{B} \cdot P(A) = \sum_{i: s_i \in A} p_i$

**Proof**  $\forall A \in \mathcal{B}, P(A) = \sum_{i: s_i \in A} p_i \geq 0$  (by  $p_i \geq 0$ )  
 $P(S) = \sum_{i \in S} p_i = \sum p_i = 1$  //  
 Axiom 3: Let  $A_1, \dots, A_k$  denote pairwise disjoint events then  $P(\bigcup A_i) = \sum_{j=1}^k \sum_{i: s_i \in A_j} p_i = \sum P(A_i)$  (Def finite disjoint)

Theorem 1.28 If  $P$  is a probability function and  $A$  is any set in  $\mathcal{B}$  then

- a)  $P(\emptyset) = 0$
- b)  $P(A) \leq 1$
- c)  $P(A^c) = 1 - P(A)$

**Proof** •  $A$  and  $A^c$  form a partition so  $S = A \cup A^c$   
 so  $P(A \cup A^c) = P(S) = 1$  (by Kolmogorov 2)  
 • Since  $A$  and  $A^c$  are disjoint  $1 = P(A \cup A^c) = P(A) + P(A^c)$   
 so  $P(A^c) = 1 - P(A)$  // c  
 •  $S \cup \emptyset = S$  so  $P(S \cup \emptyset) = P(S) = 1$  (Kolmogorov 2)  
 • Since  $S$  and  $\emptyset$  are disjoint  $1 = P(S \cup \emptyset) = P(S) + P(\emptyset)$   
 so  $P(\emptyset) = 0$  // a  
 • Since  $P(A^c) = 1 - P(A)$   $P(A) = 1 - P(A^c)$   
 $P(A^c) \geq 0$  (by 1.24 a)  
 so  $P(A) \leq 1$  // b

Bonferroni's Inequality  $P(A \cap B) \geq P(A) + P(B) - 1$

NOTE: USEFUL FOR LARGE  $P(A)$  and  $P(B)$

**Proof**  $P(A \cup B) = P(A) + P(B) - P(A \cap B)$   
 $P(A \cap B) = P(A) + P(B) - P(A \cup B)$  (rearranging)  
 $P(A \cap B) \geq P(A) + P(B) - 1$  (b/c  $P(A \cup B) \leq 1$ ) (1.24 a)

**Theorem 1.2.9** If  $P$  is a probability function and **Proof**  $P(B) = P(B \cap A) \cup (B \cap A^c)$  [b/c p. 2  $B = (B \cap A) \cup (B \cap A^c)$ ]  
 $= P(B \cap A) + P(B \cap A^c)$  [b/c they are disjoint]  
 $\circ \circ P(B \cap A^c) = P(B) - P(B \cap A)$  // a  
 A and B are sets in  $\mathcal{B}$  then  
 a.  $P(B \cap A^c) = P(B) - P(A \cap B)$   
 b.  $P(A \cup B) = P(A) + P(B) - P(A \cap B)$   
 c. If  $A \subseteq B$  then  $P(A) \leq P(B)$   
 $\circ P(A \cup B) = P(A) + P(B \cap A^c)$  [b/c by 2 a & 1  $A, A^c$  are disjoint]  
 $= P(A) + P(B) - P(A \cap B)$  by a // b  
 • If  $A \subseteq B$  then  $A \cap B = A$   
 $0 \leq P(B \cap A^c) = P(B) - P(A)$  (by above and a + def 1.2.4)  
 $\circ \circ P(A) \leq P(B)$  // c

**Theorem 1.2.11** If  $P$  is a probability function then **Proof**  
 a)  $P(A) = \sum_i P(A \cap C_i)$  for any partition  $C_1, \dots, C_n$  on  $S$   
 b)  $P(\bigcup_i A_i) \leq \sum_i P(A_i)$  for  $A_1, A_2, \dots$   
 NOTE  $A \cap B = A \cap B^c$   
 • Since  $C_i$  forms a partition  $C_i \cap C_j = \emptyset \forall i \neq j$   
 and  $\bigcup_i C_i = S$  so  $A = A \cap S = A \cap (\bigcup_i C_i) = \bigcup_i (A \cap C_i)$   
 $\circ \circ P(A) = \sum_i P(A \cap C_i)$  // a  
 • Let  $A_1^*, A_2^*, \dots$  be a disjoint collection  $\Rightarrow \bigcup_i A_i^* = \bigcup_i A_i$   
 •  $A_1^* = A_1, A_i^* = A_i \setminus (\bigcup_{j=1}^{i-1} A_j)$   $i=2,3,\dots$   
 $\circ \circ P(\bigcup_i A_i) = P(\bigcup_i A_i^*) = \sum_i P(A_i^*)$  since  $(A_i^*)$  are disjoint  
 •  $A_i^* \subseteq A_i$  so  $P(A_i^*) \leq P(A_i)$   
 $\circ \circ \sum_i P(A_i^*) \leq \sum_i P(A_i)$   
 $\circ \circ P(\bigcup_i A_i) \leq \sum_i P(A_i)$  for  $A_1, A_2, \dots$  // b  
 Doesn't  $A_i$  have to be disjoint?  $\rightarrow$

**Theorem 1.2.14** If a job consists of  $k$  separate tasks the  $i^{\text{th}}$  of which can be done in  $n_i$  ways  $\forall i=1,2,\dots,k$  then the entire job can be done in  $n_1 \times n_2 \times \dots \times n_k$  ways  
**Proof** Base cases:  $k=1$  we can do 1 job  $n_1$  ways  
 $k=2$   $n_1, n_2$  ways  $\rightarrow n_1 \times n_2$  ways by counting  
 Assume:  $k=n$   $n_1, n_2, \dots, n_n$  ways  $\rightarrow n_1 \times n_2 \times \dots \times n_n$  ways  
 Show:  $k=n+1$   $n_1, n_2, \dots, n_n, n_{n+1}$  ways  $\rightarrow n_1 \times n_2 \times \dots \times n_n \times n_{n+1}$  ways  
 $k_{n+1}$  ways = (ways to do  $k_n$  ways)  $\times$  ( $n_{n+1}$ ) (by counting)  
 $= (n_1 \times n_2 \times \dots \times n_n) \times n_{n+1}$  // EMS

Counting w/ replacement - choice is the same each time you make it (ie chosen items are replaced restoring original set)

Counting w/o replacement - choice is different each time as the original set changes w/ every choice

Ordered - the order of the choices matter (Powerball)

Unordered - the order of the choices doesn't matter (3 play w box option)

Def 1.2.16 For  $n > 0$ ,  $n! = n \cdot (n-1) \cdot (n-2) \cdots 1$ . For  $n=0$ ,  $0! = 1$

Counting Procedures w/  $n$  items and  $r$  selections

- Ordered w/o replacement:  $nPr = \frac{n!}{(n-r)!}$
- Ordered w/ replacement:  $n^r$
- Unordered w/o replacement:  $nCr = \binom{n}{r} = \frac{n!}{r!(n-r)!}$
- Unordered w/ replacement:  $n+r-1Cr = \frac{(n+r-1)!}{r!(n-1)!}$

Def If all outcomes are equally likely i.e.  $P(s_i) = \frac{1}{n} \forall s_1, s_2, \dots, s_n$  then  
 $P(A) = \sum_{s_i \in A} P(s_i) = \sum \frac{1}{n} = \frac{\# \text{ of elements in } A}{\# \text{ of elements in } S}$

**1.3**

Def 1.3.2 •  $P(A|B) = \text{Prob of } A \text{ given that } B \text{ has occurred} = \frac{P(A \cap B)}{P(B)}$   
 •  $P(A \cap B) = P(A|B)P(B) = P(B|A)P(A)$

Def 1.3.5 •  $P(A|B) = P(B|A) \frac{P(A)}{P(B)}$  by rearranging the above

Theorem 1.3.5 Bayes' Rule: Let  $P(A_i|B) = \frac{P(B|A_i)P(A_i)}{\sum P(B|A_j)P(A_j)}$  for  $A_i$  a partition of  $S$

**Proof**  $P(A|B) = \frac{P(A \cap B)}{P(B)}$  by def 1.3.5 and disjointness  
 $P(B|A) = \frac{P(A \cap B)}{P(A)}$   
 $\therefore P(A|B)P(B) = P(A \cap B) = P(B|A)P(A)$   
 $\therefore P(A|B) = \frac{P(A \cap B)}{P(B)}$   
 $P(B) = \sum (B \cap A_i)$  (by 1.2.11 b/c  $A$  is a partition)  
 $(B \cap A_i) = P(B|A_i)P(A_i)$  (by 1.3.2)  
 $P(A \cap B) = P(B|A)P(A)$  (by 1.3.2)  
 $\therefore \frac{P(A \cap B)}{P(B|A)P(A)} = P(B|A)P(A)$  by substitution // ems

Def 1.3.7  $A, B$  are statistically independent if  $P(A \cap B) = P(A)P(B)$

**Proof**  $P(A \cap B) = P(A|B)P(B)$   
 $P(A|B) = P(A)$  if  $A, B$  are independent  
 $\therefore$  If independent  $P(A \cap B) = P(A)P(B)$  // ems

$\equiv P(A|B) = P(A)$   
 $\equiv P(B|A) = P(B)$

Theorem 1.3.9: If A and B are independent events Proof  $P(A \cap B^c) = P(A)P(B^c)$  (Want to show)  
 then the following are also independent

- a) A and  $B^c$
- b)  $A^c$  and B
- c)  $A^c$  and  $B^c$

$$\begin{aligned}
 P(A \cap B^c) &= P(A) - P(A \cap B) \quad (\text{Theorem 1.2.9a}) \\
 &= P(A) - P(A)P(B) \quad (\text{b/c } A \text{ \& } B \text{ are ind}) \\
 &= P(A)(1 - P(B)) \quad (\text{dist}) \\
 &= P(A)P(B^c) \quad (\text{complement}) // a
 \end{aligned}$$

$$\begin{aligned}
 P(B \cap A^c) &= P(B) - P(B \cap A) \\
 &= P(B) - P(B)P(A) \quad (\text{b/c } A \text{ \& } B \text{ are ind}) \\
 &= P(B)(1 - P(A)) \quad (\text{dist}) \\
 &= P(B)P(A^c) \quad (\text{complement}) // b
 \end{aligned}$$

$$\begin{aligned}
 P(A^c \cap B^c) &= P(A^c)P(B^c) \quad (\text{WTS}) \\
 &= P(A^c) - P(A^c \cap B) \quad (\text{artful complication}) \\
 &= P(A^c) - P(A^c)P(B) \quad (\text{by b}) \\
 &= P(A^c)(1 - P(B)) \quad (\text{distribution}) \\
 &= P(A^c)P(B^c) \quad (\text{complement}) // c
 \end{aligned}$$

Definition 1.3.12: A collection of events  $A_1, \dots, A_n$  mutually independent for any sub collection  $A_{i_1}, A_{i_2}, \dots, A_{i_k}$   
 then we have:  $P(\bigcap_{j=1}^k A_{i_j}) = \prod_{j=1}^k P(A_{i_j})$

### 1.3 w/ $\sigma$ algebras

from  $(\Omega, \mathcal{B}, P)$  <sup>sample space</sup>  $\rightarrow P(A|B) = \frac{P(A \cap B)}{P(B)}$  Assuming  $P(B) > 0$   
 $\equiv$  from  $(B, \mathcal{B}_B, P_B)$   <sup>$\sigma$  algebra  $\subseteq \mathcal{B}$</sup>   $\rightarrow P(A|B) = P_B(A \cap B) \quad \forall A \cap B \in \mathcal{B}_B$   
subset provided by given event

Add to 1.2.11

$$\begin{aligned}
 P(A) &= \sum_i P(A \cap C_i) \quad (\text{by theorem 1.2.11}) \\
 &= \sum_i P(A|C_i)P(C_i) \quad (\text{Multiplication Rule})
 \end{aligned}$$

- Pairwise independent if:
  - 1)  $P(A \cap B) = P(A)P(B)$
  - 2)  $P(A \cap C) = P(A)P(C)$
  - 3)  $P(B \cap C) = P(B)P(C)$

- Mutually independent if: 1-3
  - 4)  $P(A \cap B \cap C) = P(A)P(B)P(C)$

1.4

Random Variable:

$X: S \Rightarrow R \hat{=} X^{-1}(B) = \{ \omega \in S \mid X(\omega) \in B \} \in \mathcal{B} \quad \forall B \in \mathcal{B}(R)$

$(S, \mathcal{B}, P) \Rightarrow (R, \mathcal{B}(R), P_X)$

Domain  $\rightarrow$  Range

NOTE 1)  $\sigma(X) = \{ X^{-1}(B) : B \in \mathcal{B}(R) \}$  is a  $\sigma$  algebra on  $S$

2)  $X^{-1}(B) = \{ \omega \in S \mid X(\omega) \in B \} \in \mathcal{B} \quad \forall B \in \mathcal{B}(R)$  says all  $\{ X \in \mathcal{B}(R) \}$  can be assigned a probability according to the measure  $P$  on  $(S, \mathcal{B})$

3)  $X$  is a  $\mathcal{B} - \mathcal{B}(R)$  measurable mapping from  $S$  to  $R$

Support of a random variable is the range i.e.  $X = \{ x_1, \dots, x_m \}$

- finite support if  $m < \infty$

- countably infinite support if  $m = \infty$

Induced Measure  $P_X(X = x_i) = P(\omega \in S \mid X(\omega) = x_i)$  measured on  $(R, \mathcal{B}(R))$  'the range'

1.5

Cumulative Distribution Function:  $F_X(x) = P(X \leq x) \leftarrow$  induced measure on  $(R, \mathcal{B}(R))$

NOTE:  $f(x)$  is defined on all  $x \in R$  not just  $X \subset X$

Theorem 1.5.3 -  $F_X: R \rightarrow [0, 1]$  is a cdf iff

a)  $\lim_{x \rightarrow -\infty} F_X(x) = 0 \quad \hat{=} \quad \lim_{x \rightarrow \infty} F_X(x) = 1$

b)  $F_X(x)$  is non decreasing

c)  $F_X(x) = P(X \leq x)$  is right continuous that is  $\lim_{x \rightarrow x_0^+} f(x) = f(x_0) \quad \forall x_0$

Proof a)  $\lim_{x \rightarrow -\infty} F_X(x) = \lim_{x \rightarrow -\infty} P(X \leq x) = 0$

$\lim_{x \rightarrow \infty} F_X(x) = \lim_{x \rightarrow \infty} P(X \leq x) = 1$

b) Let  $x_0 \leq x_1$  then  $F(x_0) = P(X \leq x_0) \leq P(X \leq x_1) = F(x_1) \Rightarrow F(x)$  is non decreasing

c)  $F(x) = P(X \leq x)$  is right continuous because we define  $F(x)$  using ' $\leq$ ' so even if  $F(x)$  is discontinuous (a step function)  $\lim_{x \rightarrow x_0^+} F(x) = F(x_0)$

Definition 1.5.3 The random variables  $X$  and  $Y$  are identically distributed if for every set  $A \in \mathcal{B}^d$ ,  $P(X \in A) = P(Y \in A)$  where  $X=Y$  or  $X \neq Y$  Denote  $(X \stackrel{d}{=} Y)$

Definition 1.5.7 A random variable is continuous if  $F(x)$  is continuous and discrete if  $F(x)$  is a step function

Theorem 1.5.10  $F_X(x) = F_Y(y) \equiv X \equiv Y$  Proof  $\Rightarrow F_X(x) = P(X \leq x) = P(Y \leq y) = F_Y(x) \forall x$   
 $\Leftarrow$  Too hard to show

1.6

Def 1.6.1 • The Probability Mass Function of a discrete random variable,  $X$ , is given by

$$f_X(x) = P(X=x) = \underset{\text{PMF}}{F_X(x)} = \sum_{t \in \mathbb{R}} \underset{\text{PMF}}{f_X(t)}$$

• If  $X$  is a continuous r.v. w/ CDF  $F_X(x)$  Proof  $\{X=x\} \equiv \{x-\epsilon < X \leq x\} \ni \forall \epsilon \text{ fix } \epsilon > 0$   
 then  $P_X(X=x) = 0 \forall x \in \mathbb{R}$   
 $P(X=x) \leq P(x-\epsilon < X \leq x)$   
 $P(X=x) = F_X(x) - F_X(x-\epsilon)$   
 $= 0$  as  $\epsilon \rightarrow 0 //$

Def 1.6.3 • The Probability Density Function of a <sup>(absolutely)</sup> continuous random variable  $X$  is given by  
 $F_X(x) = \underset{\text{CDF}}{\int_{-\infty}^x f(x) dx}$

Theorem 1.6.5 • Properties of PDF/PMF valid iff

a)  $f_X(x) \geq 0 \forall x \in \mathbb{R}$

b) discrete:  $\sum_{x \in \mathbb{R}} f_X(x) = 1$

continuous:  $\int_{\mathbb{R}} f_X(x) dx = 1$

Proof  $\Rightarrow$  discrete:  $f_X(x) = P(X=x) \geq 0$   
 $\sum_{\mathbb{R}} f_X(x) = \sum_{\mathbb{R}} P_X(X=x) = 1$

continuous:  $f_X(x) \geq 0$  (b/c = derivative of CDF) <sup>non-decreasing</sup>  
 $\int_{\mathbb{R}} f_X(x) dx = \lim_{x \rightarrow \infty} F_X(x) \stackrel{!}{=} 1 //$

$\Leftarrow$



2.1

Binomial Transformation  $f_x(x) = P(X=x) = \binom{n}{x} p^x (1-p)^{n-x}$   $x=0, 1, \dots, n$

Uniform Transformation  $f_x(x) = \frac{1}{2\pi}$   $0 < x < 2\pi$

Theorem 2.1.3 Let  $X$  have cdf  $F_X(x)$ , let  $Y=g(X)$  and let  $X = \{x | f_X(x) > 0\}$  &  $Y = \{y | y=g(x) \text{ for } x \in X\}$   
Then a) If  $g$  is an increasing function on  $X$   $F_Y(y) = F_X(g^{-1}(y))$  for  $y \in Y$   
b) If  $g$  is a decreasing function on  $X$   $F_Y(y) = 1 - F_X(g^{-1}(y))$   $y \in Y$

Theorem 2.1.5 Let  $X$  have pdf  $f_X(x)$  and  $Y=g(X)$  &  $g(x)$  is a monotone function. Let  $X = \{x | f_X(x) > 0\}$  &  $Y = \{y | y=g(x) \text{ for } x \in X\}$ . Suppose that  $f_X(x)$  is continuous on  $X$  and that  $g^{-1}(y)$  has a continuous derivative on  $Y$  then  
$$f_Y(y) = \begin{cases} f_X(g^{-1}(y)) \left| \frac{d}{dy} g^{-1}(y) \right| & y \in Y \\ 0 & \text{otherwise} \end{cases}$$

↑ This comes directly from Theorem 2.1.3

Theorem 2.1.8 Let  $X$  have pdf  $f_X(x)$ , let  $Y=g(X)$  and  $X = \{x | f_X(x) > 0\}$ . Suppose  $\exists$  a partition  $A_0, A_1, A_2, \dots, A_n$  of  $X \Rightarrow P(X \in A_0) = 0$ , and  $f_X(x)$  is continuous on each  $A_i$ . Also suppose  $\exists$  functions  $g_1(x), \dots, g_k(x)$  on  $A_1, \dots, A_n$  respectively  $\circ$

i)  $g(x) = g_i(x) \quad \forall x \in A_i$

ii)  $g_i(x)$  is monotone on  $A_i$

iii) The set  $Y = \{y | y = g_i(x) \text{ for some } x \in A_i\}$  is the same for each  $i=1, \dots, k$

iv)  $g^{-1}(y)$  has a continuous derivative on  $Y \quad \forall i=1, \dots, k$

$$f_Y = \begin{cases} \sum_{i=1}^k f_X(g_i^{-1}(y)) \left| \frac{d}{dy} g_i^{-1}(y) \right| & y \in Y \\ 0 & \text{otherwise} \end{cases}$$

Theorem 2.1.10 Let  $X$  have continuous cdf  $F_X(x)$  and define the random variable  $Y$  as  $Y = F_X(x)$  then  $Y$  is uniformly distributed on  $(0,1)$  that is  $P(Y=y) = y$  for  $0 \leq y \leq 1$   
 • Proof pg 54

## 2.2

Def 2.2.1 Expected Value =  $E(X)$  = The mean of a random variables  
 • Discrete:  $E(g(x)) = \sum_{x \in \mathcal{X}} g(x) f_X(x)$   
 • Continuous:  $E(g(x)) = \int_{-\infty}^{\infty} g(x) f_X(x) dx$

Theorem 2.2.5 Let  $X$  be a random variable and let  $a, b, c$  be constants then for any functions  $g_1$  and  $g_2$  whose expectations exist (finite)

- $E(ag_1(x) + bg_2(x) + c) = aE(g_1(x)) + bE(g_2(x)) + c$
- if  $g_1(x) \geq 0 \forall x$  then  $E(g_1(x)) \geq 0$
- if  $g_1(x) \geq g_2(x) \forall x$  then  $E(g_1(x)) \geq E(g_2(x))$
- if  $a \leq g_1(x) \leq b \forall x$  then  $a \leq E(g_1(x)) \leq b$

• For  $Y = g(X)$ :

$$E(Y) = \int_{-\infty}^{\infty} Y f_Y(y) dy$$

$$E(Y) = \int_{-\infty}^{\infty} g(x) f_X(x) dx$$

## 2.3

Def 2.3.1 •  $K^{\text{th}}$  moment =  $\mu'_K = E(X^K)$   
 •  $K^{\text{th}}$  central moment =  $\mu_K = E((X - \mu)^K)$

Def 2.3.2 • The variance of a random variable  $X$  is its second central moment  
 $\text{Var}(X) = E((X - E(X))^2) = E(X^2) - (E(X))^2$   
 • The positive square root of the  $\text{var}(X)$  is the std. deviation

Theorem 2.3.4  $\text{Var}(aX + b) = a^2 \text{Var} X$

Proof  $E((aX + b) - E(aX + b))^2$   
 $= E(aX - aE(X))^2$   
 $= a^2 E(X - E(X))^2$   
 $= a^2 \text{var}(X) //$

Def 2.3.6 Let  $X$  be a random variable with cdf  $F_X$ . The moment generating function, mgt, of  $X$  (or  $F_X$ ) denoted by  $M_X(t)$  is  $M_X(t) = E(e^{tx})$  provided the expectation exists for  $t$  in some neighborhood of 0. i.e.  $\exists h > 0 \ni \forall t \in (-h, h)$   $E(e^{tx})$  exists, otherwise DNE

Continuous:  $M_X(t) = \int_{-\infty}^{\infty} e^{tx} f_X(x) dx$   
 Discrete:  $M_X(t) = \sum e^{tx} f_X(x) dx$

Theorem 2.3.7 If  $X$  has mgt  $M_X(t)$  then  $E(X^n) = M_X^{(n)}(0) = \left. \frac{d^n}{dt^n} M_X(t) \right|_0$   
 Proof p. 62

Theorem 2.3.11 Let  $F_X(x)$  and  $F_Y(y)$  be two cdfs whose moments exist

a) If  $X$  and  $Y$  have bounded support then  $F_X(u) = F_Y(u) \forall u$  iff  $E(X^r) = E(Y^r)$  for  $r = 0, 1, 2, \dots$

b) If the mgt's exist and  $M_X(t) = M_Y(t) \forall t$  in some neighborhood of 0 then  $F_X(u) = F_Y(u) \forall u$

Theorem 2.3.12 Suppose  $\{X_i, i = 1, 2, \dots\}$  is a sequence of random variables each with mgt  $M_{X_i}(t)$ . Further suppose that  $\lim_{i \rightarrow \infty} M_{X_i}(t) = M_X(t) \forall t$  in a neighborhood of zero and  $M_X(t)$  is an mgt. Then  $\exists$  a unique cdf  $F_X$  whose moments are determined by  $M_X(t)$  and,  $\forall x \ni F_X$  is continuous we have  $\lim_{i \rightarrow \infty} F_{X_i}(x) = F_X(x)$

Lemma 2.3.14 Let  $a_1, a_2, \dots$  be a sequence of numbers converging to  $a$ , that is,  $\lim_{n \rightarrow \infty} a_n = a$  then  $\lim_{n \rightarrow \infty} \left(1 + \frac{a_n}{n}\right)^n = e^a$

Theorem 2.3.15 For any constants  $a$  and  $b$  the mgt of the random variable  $aX+b$  is  $M_{aX+b}(t) = e^{bt} M_X(at)$   
 Proof p. 68

## 2.4

Theorem 2.4.1 If  $f(x, \theta)$ ,  $a(\theta)$  and  $b(\theta)$  are differentiable w/ respect to  $\theta$  then

$$\frac{d}{d\theta} \int_{a(\theta)}^{b(\theta)} f(x, \theta) dx = f(b(\theta), \theta) \frac{d}{d\theta} b(\theta) - f(a(\theta), \theta) \frac{d}{d\theta} a(\theta) + \int_{a(\theta)}^{b(\theta)} \frac{\partial}{\partial \theta} f(x, \theta) dx$$

Leibniz's Rule ~~\*\*~~ when  $a(\theta)$  and  $b(\theta)$  are constants  $\frac{d}{d\theta} \int_{a(\theta)}^{b(\theta)} f(x, \theta) dx = \int_{a(\theta)}^{b(\theta)} \frac{\partial}{\partial \theta} f(x, \theta) dx$  ~~\*\*~~

Theorem 2.4.2 Suppose  $h(x, y)$  is continuous at  $y_0 \forall x$  and  $\exists$  a function  $g(x)$  that satisfies

- i)  $|h(x, y)| \leq g(x) \forall x$  and  $y$
- ii)  $\int_{-\infty}^{\infty} g(x) dx < \infty$

then  $\lim_{y \rightarrow y_0} \int_{-\infty}^{\infty} h(x, y) dx = \int_{-\infty}^{\infty} \lim_{y \rightarrow y_0} h(x, y) dx$

Theorem 2.4.3 Suppose  $f(x, \theta)$  is differentiable at  $\theta = \theta_0$ , that is  $\lim_{\delta \rightarrow 0} \frac{f(x, \theta_0 + \delta) - f(x, \theta_0)}{\delta} = \frac{d}{d\theta} f(x, \theta) \Big|_{\theta = \theta_0}$  exists  $\forall x$  and  $\exists$  a function  $g(x, \theta_0)$  and a constant  $\delta_0 \geq 1 \Rightarrow$

- i)  $\frac{f(x, \theta_0 + \delta) - f(x, \theta_0)}{\delta} \leq g(x, \theta_0) \forall x$  and  $|\delta| \leq \delta_0$

ii)  $\int_{-\infty}^{\infty} g(x, \theta_0) dx < \infty$   
 then  $\frac{d}{d\theta} \int_{-\infty}^{\infty} f(x, \theta) dx \Big|_{\theta = \theta_0} = \int_{-\infty}^{\infty} \left[ \frac{d}{d\theta} f(x, \theta) \Big|_{\theta = \theta_0} \right] dx$

Corollary 2.4.4 Suppose  $f(x, \theta)$  is differentiable in  $\theta$  and  $\exists g(x, \theta) = \left[ \frac{d}{d\theta} f(x, \theta) \right]_{\theta = \theta'}$   
 $\forall \theta' \ni |\theta' - \theta| \leq \delta_0$  and  $\int_{-\infty}^{\infty} g(x, \theta) dx < \infty$  2.4.3 holds

Theorem 2.4.8 Suppose that the series  $\sum_{n=0}^{\infty} h_n(\theta, x)$  converges for all  $\theta$  in an interval  $(a, b)$  of real numbers and

- i)  $\frac{\partial}{\partial \theta} h_n(\theta, x)$  is continuous in  $\theta$  for each  $x$
- ii)  $\sum_{n=0}^{\infty} \frac{\partial}{\partial \theta} h_n(\theta, x)$  converges uniformly on every closed and bounded subinterval of  $(a, b)$

Then  $\frac{\partial}{\partial \theta} \sum_{n=0}^{\infty} h_n(\theta, x) = \sum_{n=0}^{\infty} \frac{\partial}{\partial \theta} h_n(\theta, x)$

Theorem 2.4.10 Suppose the series  $\sum_{n=0}^{\infty} h_n(\theta, x)$  converges uniformly on  $[a, b]$  and that  $\forall x, h_n(\theta, x)$  is a continuous function of  $\theta$  then

$$\int_a^b \sum_{n=0}^{\infty} h_n(\theta, x) d\theta = \sum_{n=0}^{\infty} \int_a^b h_n(\theta, x) dx$$

## 2.6

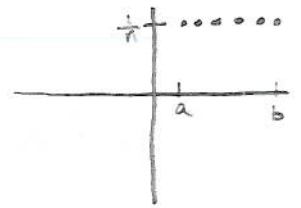
- A distribution is not necessarily determined by its moments
- Cumulant generating function =  $\log [M_X(t)]$
- Factorial mgf =  $E(t^x)$

## Chapter 3

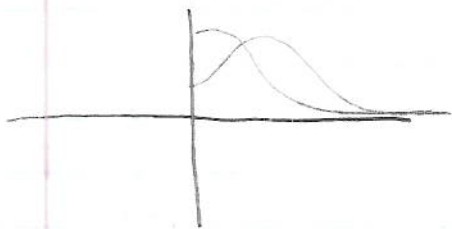
Family - type of distribution whose members are decided by parameters  
Discrete Distribution if its support set is countable

Discrete Uniform  $(1, N)$ ,  $X = 1, 2, \dots, N$ ,  $P(X=x|N) = \frac{1}{N}$

- This distribution puts equal weights on each outcome
- $E(x) = \sum_{x=1}^N x P(X=x|N) = \frac{N+1}{2}$
- $E(x^2) = \sum_{x=1}^N x^2 P(X=x|N) = \frac{(N+1)(2N+1)}{6}$
- $\text{Var}(x) = \frac{(N+1)(N-1)}{12}$



## Hypergeometric Distribution



- This distribution is used in the 'urn model'
- We have an urn w/  $N$  balls ( $M$  red,  $N-M$  green) we then select  $k$  balls at random - what is the probability that  $x$  of the  $k$  balls are red

• # of samples of size  $k$   $\binom{N}{k}$

• # of ways  $x$  of  $M$  balls are red  $\binom{M}{x}$

and  $k-x$  green

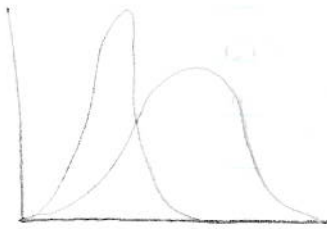
$$\bullet P(X=x|N, M, k) = \frac{\binom{M}{x} \binom{N-M}{k-x}}{\binom{N}{k}} \quad x = 0, 1, \dots, k$$

$$\bullet E(x) = \sum_{x=0}^k x P(X=x|N, M, k)$$

$$\bullet E(x^2) = \sum_{x=0}^k x^2 P(X=x|N, M, k)$$

$$\bullet \text{Var}(x) = \frac{kM}{N} \left( \frac{(N-M)(N-k)}{N-1} \right)$$

## Binomial Distribution



• Based on Bernoulli trials (Success/fail)

•  $X = \begin{cases} 1 & \text{w/ probability } p \\ 0 & \text{w/ probability } 1-p \end{cases}$  // success  
// failure

$$\cdot P(X=y|n,p) = \binom{n}{y} p^y (1-p)^{n-y} \quad y=0,1,2,\dots,n$$

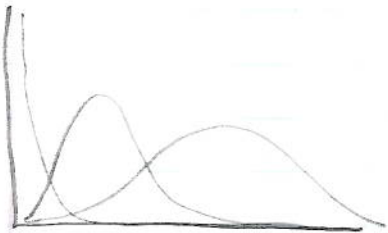
$$\cdot E(X) = np$$

$$\cdot \text{var}(X) = np(1-p)$$

• All trials must be identical, independent and of fixed size

$$\cdot M_X(t) = [(1-p) + pe^t]^n$$

## Poisson Distribution



• used for wait time and spatial statistics

$$\cdot P(X=x|\lambda) = \frac{e^{-\lambda} \lambda^x}{x!} \quad x=0,1,\dots \quad \lambda = \text{intensity}$$

$$\cdot E(X) = \lambda$$

$$\cdot \text{var}(X) = \lambda$$

$$\cdot M_X(t) = e^{\lambda(e^t-1)}$$

## Negative Binomial Distribution



• Just about the opposite of a binomial

• Concerned with # of Bernoulli trials to see  $x$  successes

① • Let  $X =$  trial at which the  $r^{\text{th}}$  success occurs

$$\cdot P(X=x|r,p) = \binom{x-1}{r-1} p^r (1-p)^{x-r} \quad x=r, r+1, \dots$$

② • Let  $X =$  # of failures before  $r^{\text{th}}$  success occurs

$$P(X=x|r,p) = \binom{r+y-1}{y} p^r (1-p)^y \quad y=0,1,\dots$$

$$E(X) = r \frac{1-p}{p}$$

$$\text{var}(X) = r \frac{1-p}{p^2}$$

$$M_X(t) = \left( \frac{p}{1-(1-p)e^t} \right)^r$$

## Geometric Distribution



• Special case of negative binomial  $r=1 \rightarrow$  trials until 1<sup>st</sup> success

$$\cdot P(X=x|p) = p(1-p)^{x-1} \quad x=1,2,3,\dots$$

$$\cdot E(X) = \frac{1}{p}$$

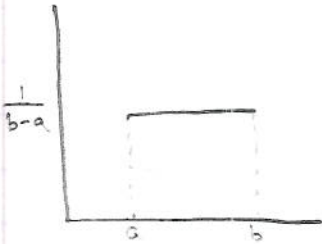
$$\cdot \text{var}(X) = \frac{1-p}{p^2}$$

$$\cdot M_X(t) = \frac{pe^t}{1-(1-p)e^t}$$

• memoryless

## Continuous Distributions

### Uniform Distribution



- Spreads mass uniformly over the interval  $[a, b]$
- $f_X(x|a, b) = \begin{cases} \frac{1}{b-a} & \text{if } x \in [a, b] \\ 0 & \text{o.w.} \end{cases}$

- $E(X) = \frac{b+a}{2}$
- $\text{Var}(X) = \frac{(b-a)^2}{12}$
- $M_X(t) = (e^{bt} - e^{at}) / ((b-a)t)$

### Gamma Distribution



- gamma function =  $\Gamma(\alpha) = \int_0^{\infty} t^{\alpha-1} e^{-t} dt$   $\alpha > 0 \in \mathbb{Z}^+$
- $\Gamma(\alpha+1) = \alpha \Gamma(\alpha)$
- $\Gamma(\frac{1}{2}) = \sqrt{\pi}$

- $f_X(x|\alpha, \beta) = \frac{1}{\Gamma(\alpha)\beta^\alpha} x^{\alpha-1} e^{-x/\beta}$   $0 < x < \infty$   $\alpha, \beta > 0$
- $\alpha$  shape
- $\beta$  scale

- $E(X) = \alpha\beta$
- $\text{Var}(X) = \alpha\beta^2$
- $M_X(t) = \left(\frac{1}{1-\beta t}\right)^\alpha$   $t < \frac{1}{\beta}$

### Chi-Squared



- Special case of gamma  $\alpha = p/2$   $\beta = 2$

- $f_X(x|p) = \frac{1}{\Gamma(p/2)2^{p/2}} x^{p/2-1} e^{-x/2}$   $0 < x < \infty$

- $E(X) = p$
- $\text{Var}(X) = 2p$
- $M_X(t) = \left(\frac{1}{1-2t}\right)^{p/2}$

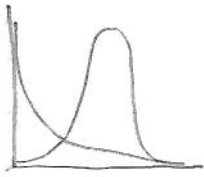
### Exponential

- Special case of gamma  $\alpha = 1$   $\beta = \beta$

- $f_X(x|\beta) = \frac{1}{\beta} e^{-x/\beta}$   $0 < x < \infty$

- $E(X) = \beta$
- $\text{Var}(X) = \beta^2$
- memoryless

### Weibull



Used for modeling hazard functions

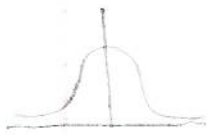
$$f(x|p) = \frac{\gamma}{\beta} x^{\gamma-1} e^{-x^\gamma/\beta} \quad x > 0, \gamma, \beta > 0$$

$$E(x) = \beta^{1/\gamma} \Gamma(1 + \frac{1}{\gamma})$$

$$\text{var}(x) = \beta^{2/\gamma} \left[ \Gamma(1 + \frac{2}{\gamma}) - \Gamma^2(1 + \frac{1}{\gamma}) \right]$$

$$M_x(t) = \beta^{1/\gamma} \Gamma(1 + \frac{t}{\gamma}) \quad \gamma \geq 1$$

### Normal



$$X \sim N(\mu, \sigma^2)$$

$$f_x(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

$$Z = \frac{x-\mu}{\sigma} \sim N(0,1) \quad \text{Standard Normal}$$

$$E(x) = \mu$$

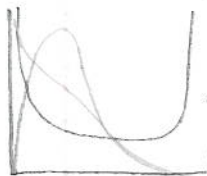
$$\text{var}(x) = \sigma^2$$

We can use the normal distribution to approximate the binomial when heuristic  $\min(np, np(1-p)) \geq 5$  i.e. large  $n$  and small  $p$

$$\text{Binomial}(n,p) \sim N(np, np(1-p))$$

### Beta

for interval data



$$f_x(x|\alpha, \beta) = \frac{1}{B(\alpha, \beta)} x^{\alpha-1} (1-x)^{\beta-1}; \quad 0 < x < 1, \alpha > 0, \beta > 0$$

$$B(\alpha, \beta) = \int_0^1 x^{\alpha-1} (1-x)^{\beta-1} dx = \frac{\Gamma(\alpha)\Gamma(\beta)}{\Gamma(\alpha+\beta)}$$

$$E(x) = \frac{\alpha}{\alpha+\beta}$$

$$\text{var}(x) = \frac{\alpha\beta}{(\alpha+\beta)^2(\alpha+\beta+1)}$$

$$M_x(t) = 1 + \sum_{r=1}^{\infty} \left( \prod_{i=0}^{r-1} \frac{\alpha+i}{\alpha+\beta+i} \right) \frac{t^r}{r!}$$

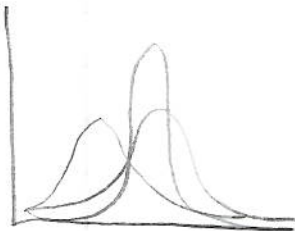
### Cauchy Dist

symmetric bellshaped on  $(-\infty, \infty)$

$$f_x(x|\theta) = \frac{1}{\pi} \frac{1}{1+(x-\theta)^2} \quad -\infty < x < \infty \quad -\infty < \theta < \infty$$

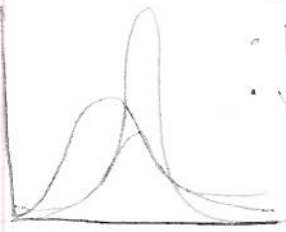
$E(x)$  DNE - We use  $\theta$  as the center of the distribution

$$P(x=\theta) = .5 \quad ; \quad P(x \neq \theta) = .5$$





Log Normal: If  $\log(x) \sim N(\mu, \sigma^2)$  \* Good for data that is skewed right



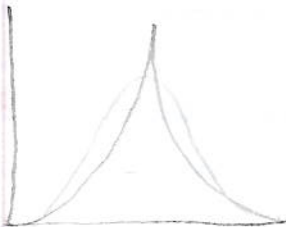
$$f(x|\mu, \sigma^2) = \frac{1}{\sigma \sqrt{2\pi}} \left(\frac{1}{x}\right) e^{-\frac{(\log(x) - \mu)^2}{2\sigma^2}} \quad 0 < x < \infty \quad -\infty < \mu < \infty \quad \sigma > 0$$

$$E(x) = e^{\mu + \frac{\sigma^2}{2}}$$

$$\text{var}(x) = e^{2(\mu + \sigma^2)} - e^{2\mu + \sigma^2}$$

$$M_x(t) = E(x^n) = e^{n\mu + \frac{n^2\sigma^2}{2}}$$

Double Exponential • Given by reflecting the exponential distribution around its mean



$$f_x(x|\mu, \sigma) = \frac{1}{2\sigma} e^{-\frac{|x-\mu|}{\sigma}}; \quad \sigma > 0$$

$$E(x) = \mu$$

$$\text{var}(x) = 2\sigma^2$$

$$M_x(t) = \frac{e^{\mu t}}{1 - (\sigma t)^2}$$

Exponential Families • distributions that can be expressed as

$$f(x|\theta) = h(x)c(\theta) \exp\left(\sum_{i=1}^k w_i(\theta) t_i(x)\right); \quad h(x) \geq 0$$

•  $t_i(x), w_i(\theta)$  are real valued funct.  
 $\theta$  no  $t_i(x)$  depends on  $\theta$

• normal, gamma, beta, binomial, poisson and negative binomial are exponential families.

• to show this we must identify the functions  $h(x), c(\theta), w_i(\theta), t_i(x)$  that can create the previous form

Theorem 3.4.2 If  $X$  is a random variable with pdf or pmf of an exponential family then

$$i) E\left(\sum_{i=1}^k \frac{\partial w_i(\theta)}{\partial \theta_j} t_i(X)\right) = \frac{\partial}{\partial \theta_j} \log c(\theta)$$

$$ii) \text{Var}\left(\sum_{i=1}^k \frac{\partial w_i(\theta)}{\partial \theta_j} t_i(X)\right) = \frac{\partial^2}{\partial \theta_j^2} \log c(\theta) - E\left(\sum_{i=1}^k \frac{\partial^2 w_i(\theta)}{\partial \theta_j^2} t_i(X)\right)$$

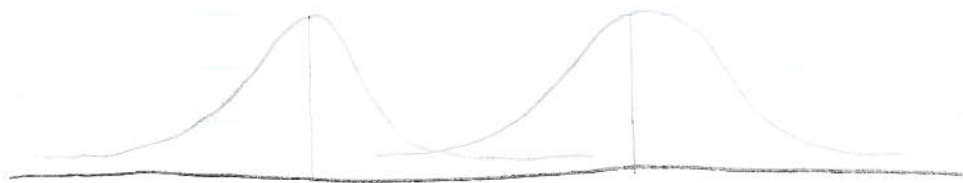
Def 3.4.7 • A curved exponential family is an exponential family for which the dimension of vector  $\Theta$  is  $d < k$

• A full exponential family is an exponential family for which the dimension of vector  $\Theta$  is  $d = k$

Theorem 3.5.1 Let  $f(x)$  be a pdf and let  $\mu, \sigma > 0$  be given constants then

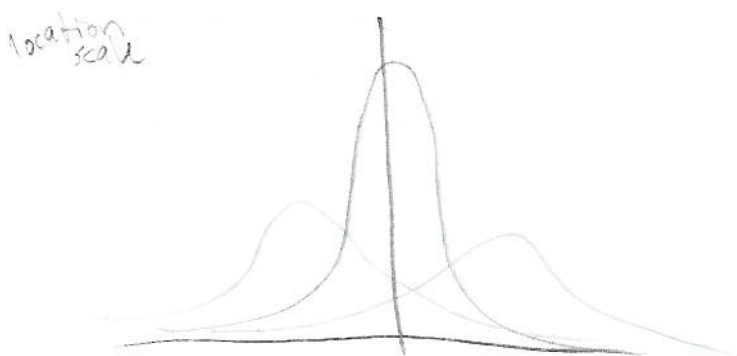
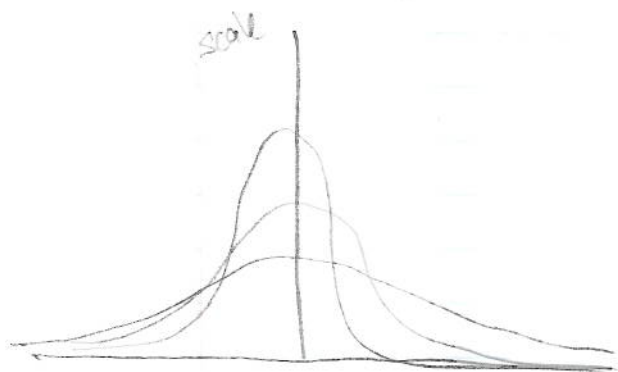
$$g(x|\mu, \sigma) = \frac{1}{\sigma} f\left(\frac{x-\mu}{\sigma}\right) \quad \text{is a pdf}$$

Def 3.5.2 Let  $f(x)$  be any pdf. Then the family of pdfs  $f(x-\mu); -\infty < \mu < \infty$  is called the location family w/ standard pdf  $f(x)$  and location parameter  $\mu$



Def 3.5.4 Let  $f(x)$  be any pdf then  $\forall \sigma > 0$ , the family of pdfs  $(1/\sigma)f(x/\sigma)$ , indexed by  $\sigma$  is called the scale family w/ standard pdf  $f(x)$  and  $\sigma$  is called the scale parameter of the family

Def 3.5.5 Let  $f(x)$  be any pdf. Then for any  $\mu, -\infty < \mu < \infty$  and any  $\sigma > 0$  the family of pdfs  $(1/\sigma)f((x-\mu)/\sigma)$  indexed by  $(\sigma, \mu)$  is called the location-scale family with standard pdf  $f(x)$  and scale parameter,  $\sigma$ , and location parameter  $\mu$ .



Theorem 3.6.1

### Chebyshev's Inequality

Let  $X$  be a random variable and  $g(x)$  be a nonnegative function then

$$\forall r > 0 \\ P(g(x) \geq r) \leq \frac{E(g(x))}{r}$$

Theorem 3.6.4

Let  $X_{\alpha, \beta}$  denote a gamma  $(\alpha, \beta)$  random variable w/ pdf  $f(x|\alpha, \beta)$  where  $\alpha \geq 1$ . Then for constants  $a$  and  $b$

$$P(a < X_{\alpha, \beta} < b) = \beta (f(a|\alpha, \beta) - f(b|\alpha, \beta)) + P(a < X_{\alpha-1, \beta} < b)$$

Lemma 3.6.5

### Stein's Lemma

Let  $X \sim N(\theta, \sigma^2)$  and let  $g$  be a differentiable function satisfying  $E(|g'(x)|) < \infty$  then

$$E[g(x)(x-\theta)] = \sigma^2 E(g'(x))$$

Theorem 3.6.7

Let  $X_p^2$  denote a chi squared RV w/  $p$  degrees of freedom for any function  $h(x)$

$$E(h(X_p^2)) = p E\left(\frac{h(X_{p+2}^2)}{X_{p+2}^2}\right)$$

Theorem 3.6.8

Hwang let  $g(x)$  be a function w/  $-\infty < E(g(x)) < \infty$  and  $-\infty < g(-1) < \infty$  then

a)  $X \sim \text{Poisson}(\lambda)$   $E(\lambda g(x)) = E(X g(x-1))$

b)  $X \sim \text{Negative Binomial}(r, p)$   $E((1-p)g(x)) = E\left(\frac{X}{r+X-1} g(x-1)\right)$

Theorem 3.8.1  
Poisson Postulates

For each  $t \geq 0$  let  $N_t$  be an integer value random variable with the following properties. (Think of  $N_t$  as # of arrivals)

i)  $N_0 = 0$  (no arrivals at start)

ii)  $s < t \rightarrow N_s$  and  $N_t - N_s$  are independent (arrivals in disjoint time periods are independent)

iii)  $N_s$  and  $N_{t+s} - N_t$  are identically distributed (depends only on period length)

iv)  $\lim_{t \rightarrow 0} \frac{P(N_t=1)}{t} = \lambda$  (arrival probability proportional to period length if length is small)

continued on next page

v)  $\lim_{t \rightarrow 0} \frac{P(N_t = 1)}{t} = 0$  (no simultaneous arrivals)

If i-v hold then for any integer  $n$

$$P(N_t = n) = e^{-\lambda t} \frac{(\lambda t)^n}{n!}$$

Theorem 3.8.2 If  $0 < \sigma < \infty$  then

- if  $n=1$  the inequality is attainable for  $k \geq 1$  and not attainable for  $0 < k < 1$
- if  $n=2$  the inequality is attainable iff  $k=1$
- if  $n \geq 3$  the inequality is not attainable

Lemma 3.8.3 Markov's inequality: If  $P(Y \geq 0) = 1$  and  $P(Y=0) < 1$  then for any  $r > 0$   $P(Y \geq r) \leq \frac{E(Y)}{r}$  with equality iff  $P(Y=r) = p = 1 - P(Y=0)$   $0 < p \leq 1$

Theorem 3.8.4

Gauss inequality Let  $X \sim f$  where  $f$  is unimodal with mode  $v$  and define  $\tau^2 = E(X-v)^2$  then

$$P(|X-v| > \epsilon) \leq \begin{cases} \frac{4\tau^2}{9\epsilon^2} & \forall \epsilon \geq \sqrt{4/3}\tau \\ 1 - \frac{\epsilon}{\sqrt{3}\tau} & \forall \epsilon \leq \sqrt{4/3}\tau \end{cases}$$

Theorem 3.8.5

Vysochanskiĭ-Petrunin Let  $X \sim f$  where  $f$  is unimodal define  $\xi^2 = E(X-\alpha)^2$  for an arbitrary point  $\alpha$  then

$$P(|X-\alpha| > \epsilon) \leq \begin{cases} \frac{4\xi^2}{9\epsilon^2} & \forall \epsilon \geq \sqrt{8/3}\xi \\ \frac{4\xi}{9\epsilon} - \frac{1}{3} & \forall \epsilon \leq \sqrt{8/3}\xi \end{cases}$$

7

Definition 4.1.1 A  $n$ -dimensional random vector is a function from a sample space into  $\mathbb{R}^n$ ,  $n$ -dimensional Euclidean space

Definition 4.1.3 Let  $(X, Y)$  be a discrete bivariate random vector. Then the function  $f(x, y)$  from  $\mathbb{R}^2$  into  $\mathbb{R}$  defined by  $f(x, y) = P(X=x, Y=y)$  is called the joint pmf of  $(X, Y) \Rightarrow f_{x,y}(x, y)$

Theorem 4.1.6 Let  $(X, Y)$  be a discrete bivariate random vector w/ joint pmf  $f_{x,y}(x, y)$ . Then the marginal pmfs of  $Y$  and  $X$  are  $f_x(x) = \sum_y f_{x,y}(x, y)$   $f_y(y) = \sum_x f_{x,y}(x, y)$

Definition 4.1.10 A function  $f(x, y)$  from  $\mathbb{R}^2$  into  $\mathbb{R}$  is called a joint pdf of the continuous bivariate RV  $(X, Y)$  if  $\forall A \subset \mathbb{R}^2$   $P((X, Y) \in A) = \iint_A f(x, y) dx dy$

Definition 4.2.1  $f(y|x) = P(Y=y|X=x) = \frac{f_{x,y}(x, y)}{f_x(x)}$   
 $\exists \int_y f(y|x) = 1$  or  $\int_x f(x|y) = 1 \quad \exists f_x(x) > 0$

Definition 4.2.5  $X, Y$  are called independent random variables if  $\forall x \in \mathbb{R}, y \in \mathbb{R} \quad f_{x,y}(x, y) = f_x(x)f_y(y)$  and  $f(y|x) = f_y(y)$

Lemma 4.2.7 Let  $(X, Y)$  be a bivariate random vector w/ joint pdf or pmf  $f_{x,y}(x, y)$  then  $X$  and  $Y$  are independent iff  $\exists g(x) \cdot h(y) \ni f(x, y) = g(x)h(y)$

proof:  $\Rightarrow \int_{-\infty}^{\infty} g(x) dx = c \quad \int_{-\infty}^{\infty} h(y) dy = d$   $\Leftarrow$  simply choose  $g(x) = f_x(x)$  and  $h(y) = f_y(y)$   
 $cd = (\int_{-\infty}^{\infty} g(x) dx) (\int_{-\infty}^{\infty} h(y) dy)$   
 $= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x)h(y) dx dy$   
 $= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f_{x,y}(x, y) dx dy$   
 $= 1$

$f_x(x) = g(x)d \quad f_y(y) = h(y)c$   
 $f(x, y) = g(x)h(y) = g(x)h(y)cd = f_x(x)f_y(y)$

Theorem 4.2.10 Let  $X$  and  $Y$  be independent random variables

a)  $\forall A \subset \mathbb{R}$  and  $B \subset \mathbb{R}$   $P(X \in A, Y \in B) = P(X \in A)P(Y \in B)$

the events  $\{X \in A\}$  and  $\{Y \in B\}$  are independent events

b) Let  $g(x)$  be a function only of  $x$  and  $h(y)$  a function only of  $y$  then  $E(g(X)h(Y)) = (E(g(X)))(E(h(Y)))$

proof  $E(g(X)h(Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x)h(y)f(x,y)dx dy$   
 $= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x)h(y)f(x)f(y)dx dy$  (independence)  
 $= \int_{-\infty}^{\infty} h(y)f(y)dy \int_{-\infty}^{\infty} g(x)f(x)dx$   
 $= \left(\int_{-\infty}^{\infty} h(y)f(y)dy\right) \left(\int_{-\infty}^{\infty} g(x)f(x)dx\right)$   
 $= E(g(X))E(h(Y))$

Theorem 4.2.12 Let  $X$  and  $Y$  be independent w/ MGFs  $M_X(t)$  and  $M_Y(t)$  then the MGF of  $Z = X + Y$  is

$$M_Z(t) = M_X(t)M_Y(t)$$

proof  $M_Z(t) = E(e^{tZ}) = E(e^{t(X+Y)}) = E(e^{tX}e^{tY}) = E(e^{tX})E(e^{tY}) = M_X(t)M_Y(t)$

Theorem 4.2.14 Let  $X \sim N(\mu, \sigma^2)$  and  $Y \sim N(\gamma, \tau^2)$  be independent then  $Z = X + Y \sim N(\mu + \gamma, \sigma^2 + \tau^2)$

Theorem 4.3.2 If  $X \sim \text{Poisson}(\theta)$  and  $Y \sim \text{Poisson}(\lambda)$  are independent then  $X + Y \sim \text{Poisson}(\theta + \lambda)$

Bivariate Transformation  $A = \{(x,y) \mid f_x(x,y) > 0\}$   
 $B = \{(u,v) \mid u = g_1(x,y) \text{ ; } v = g_2(x,y)\}$

$$u = g_1(x,y) \quad v = g_2(x,y)$$

$$x = h_1(u,v) \quad y = h_2(u,v)$$

$$J = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}$$

Then  $f_{u,v}(u,v) = f_{x,y}(h_1(u,v), h_2(u,v)) |J|$

Theorem 4.3.5 Let  $X$  and  $Y$  be independent. Let  $g(x)$  be a function only of  $x$  and  $h(y)$  be a function of only  $y$ . Then  $U = g(X)$  and  $V = h(Y)$  are independent

Theorem 4.4.3 If  $X$  and  $Y$  are any two random variables then  $E(X) = E(E(X|Y))$  provided the expectations exist

Definition 4.4.4 A random variable  $X$  is said to have a mixture distribution if the distribution of  $X$  depends on a quantity that also has a distribution.

ie  $X|Y \sim \text{binomial}$

$Y|A \sim \text{Poisson}(N)$

$A \sim \text{exponential}(\beta)$

Theorem 4.4.4 For any RV  $X$  and  $Y$   
 $\text{Var}(X) = E(\text{Var}(X|Y)) + \text{Var}(E(X|Y))$

Definition 4.5.1 The covariance of  $X$  and  $Y$   
 $\text{Cov}(X, Y) = E((X - \mu_X)(Y - \mu_Y))$

Definition 4.5.2 The correlation of  $X$  and  $Y$   
 $\rho_{xy} = \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y}$

Theorem 4.5.5 If  $X$  and  $Y$  are independent then  $\text{cov}(x, y) = 0$  and

proof  $\rho_{xy} = 0$   
 $\text{Cov}(X, Y) = E((X - \mu_X)(Y - \mu_Y)) = E(XY) - \mu_Y E(X) - \mu_X E(Y) + \mu_X \mu_Y$   
 $= E(XY) - \mu_Y \mu_X - \mu_X \mu_Y + \mu_X \mu_Y$   
 $= E(XY) - \mu_X \mu_Y$   
 $= E(X)E(Y) - \mu_X \mu_Y$   
 $= \mu_X \mu_Y - \mu_X \mu_Y$   
 $= 0$

Theorem 4.5.3  $\text{Cov}(X, Y) = E(XY) - \mu_X \mu_Y$

Theorem 4.5.6 If  $X$  and  $Y$  are any RV and  $a, b \in \mathbb{R}$   
 $\text{Var}(aX + bY) = a^2 \text{Var}(X) + b^2 \text{Var}(Y) + 2ab \text{Cov}(X, Y)$   
Note:  $2ab \text{Cov}(X, Y) = 0$  if  $X \perp Y$

Theorem 4.5.7 For any RV  $X$  and  $Y$   
a)  $-1 \leq \rho_{XY} \leq 1$   
b)  $|\rho_{XY}| = 1$  iff  $\exists a \neq 0$  and  $b \ni P(Y = aX + b) = 1$   
Note  $a > 0$  if  $\rho_{XY} = 1$   
 $a < 0$  if  $\rho_{XY} = -1$

Definition 4.5.10 Let  $-\infty < \mu_X < \infty$ ,  $-\infty < \mu_Y < \infty$ ,  $0 < \sigma_X$ ,  $0 < \sigma_Y$   
and  $-1 < \rho < 1$  the bivariate normal pdf is

$$f(x, y) = \frac{1}{2\sigma_X \sigma_Y \sqrt{1 - \rho^2}} e^{-\frac{1}{2(1 - \rho^2)} \left( \left( \frac{x - \mu_X}{\sigma_X} \right)^2 - 2\rho \left( \frac{x - \mu_X}{\sigma_X} \right) \left( \frac{y - \mu_Y}{\sigma_Y} \right) + \left( \frac{y - \mu_Y}{\sigma_Y} \right)^2 \right)}$$

Note a) the marginal distribution of  $X$  is  $N(\mu_X, \sigma_X^2)$   
b) " " " of  $Y$  is  $N(\mu_Y, \sigma_Y^2)$   
c)  $\rho_{XY} = \rho$

\* This can be expanded to more than 2 variables \*  
ie

- Random Vector  $(X_1, X_2, \dots, X_n)$
- Joint PMF/PDF  $f_X(x_1, x_2, \dots, x_n)$
- $P(X \in A) = \iiint_A f_X(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n$
- $E(g(X)) = \iiint_{\mathbb{R}^n} g(X) f_X(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n$
- Marginals:  $f(x_1, x_2, \dots, x_k) = \iiint f_X(x_1, x_2, \dots, x_n) dx_{k+1} dx_{k+2} \dots dx_n$  continuous  
 $= \sum_{x_{k+1}, x_{k+2}, \dots, x_n} f_X(x_1, x_2, \dots, x_n)$  discrete

$$f_X(x_{k+1}, x_{k+2}, \dots, x_n | x_1, x_2, \dots, x_k) = \frac{f(x_1, x_2, \dots, x_n)}{f(x_1, x_2, \dots, x_k)}$$



Definition 4.6.2 Let  $n$  and  $m$  be positive integers and let  $p_1, p_2, \dots, p_n$  be numbers satisfying  $0 \leq p_i \leq 1 \forall i=1, 2, \dots, n$  and  $\sum_{i=1}^n p_i = 1$  then the random vector  $(X_1, X_2, \dots, X_n)$  has a multinomial distribution with  $m$  trials and cell probabilities  $p_1, p_2, \dots, p_n$  and

$$f_{\underline{X}}(x_1, x_2, \dots, x_n) = \frac{m!}{x_1! \cdot x_2! \cdot \dots \cdot x_n!} p_1^{x_1} \cdot p_2^{x_2} \cdot \dots \cdot p_n^{x_n} = m! \prod_{i=1}^n \left[ \frac{p_i^{x_i}}{x_i!} \right]$$

Theorem 4.6.4 Multinomial Theorem Let  $m, n \in \mathbb{Z}^+$ ,  $A$  be the set of vectors  $\underline{x} = (x_1, x_2, \dots, x_n) \ni$  each  $x_i$  is a non negative integer and  $\sum_{i=1}^n x_i = m$  then for any  $p_1, p_2, \dots, p_n \in \mathbb{R}$

$$(p_1 + p_2 + \dots + p_n)^m = \sum_{\underline{x} \in A} \left[ \frac{m!}{x_1! \cdot x_2! \cdot \dots \cdot x_n!} p_1^{x_1} \cdot p_2^{x_2} \cdot \dots \cdot p_n^{x_n} \right]$$

Definition 4.6.5 Let  $\underline{X}_1, \underline{X}_2, \dots, \underline{X}_n$  be random vectors w/ joint pmf or pdf  $f(\underline{X}_1, \underline{X}_2, \dots, \underline{X}_n)$ . These are considered mutually independent if  $\forall (\underline{X}_1, \underline{X}_2, \dots, \underline{X}_n)$

$$f(\underline{X}_1, \underline{X}_2, \dots, \underline{X}_n) = f_{\underline{X}_1}(\underline{X}_1) \cdot f_{\underline{X}_2}(\underline{X}_2) \cdot \dots \cdot f_{\underline{X}_n}(\underline{X}_n) = \prod_{i=1}^n f_{\underline{X}_i}(\underline{X}_i)$$

Theorem 4.6.6 Let  $X_1, X_2, \dots, X_n$  be mutually independent. Let  $g_1, g_2, \dots, g_n$  be real valued functions  $\ni g_i(x_i)$  is a function only of  $x_i \quad i=1, 2, \dots, n$  then

$$E(g_1(\underline{X}_1) \cdot g_2(\underline{X}_2) \cdot \dots \cdot g_n(\underline{X}_n)) = (E(g_1(\underline{X}_1))) \cdot (E(g_2(\underline{X}_2))) \cdot \dots \cdot (E(g_n(\underline{X}_n)))$$

Theorem 4.6.7 Let  $X_1, X_2, \dots, X_n$  be mutually independent w/ MGFs  $M_1(t), M_2(t), \dots, M_n(t)$ . Let  $Z = X_1 + X_2 + \dots + X_n$  then the MGF of  $Z$  is

$$M_Z(t) = M_{X_1}(t) \cdot M_{X_2}(t) \cdot \dots \cdot M_{X_n}(t) \\ = (M_X(t))^n \quad (\text{if } x \text{ are iid})$$

Corollary 4.6.9 Let  $X_1, X_2, \dots, X_n$  be mutually independent w/ MGFs  $M_{X_1}(t), M_{X_2}(t), \dots, M_{X_n}(t)$ . Let  $a_1, a_2, \dots, a_n$  and  $b_1, b_2, \dots, b_n$  be fixed constants. Let  $Z = (a_1 X_1 + b_1) + \dots + (a_n X_n + b_n)$  then the MGF of  $Z$  is

$$M_Z(t) = \left( e^{t \sum b_i} \right) M_{X_1}(a_1 t) \cdot M_{X_2}(a_2 t) \cdots M_{X_n}(a_n t)$$

Corollary 4.6.10 Let  $X_1, X_2, \dots, X_n$  be mutually independent w/  $X_i \sim N(\mu_i, \sigma_i^2)$  then, for fixed constants  $a_1, a_2, \dots, a_n$  and  $b_1, b_2, \dots, b_n$

$$Z = \sum_i (a_i X_i + b_i) \sim N\left(\sum_i (a_i \mu_i + b_i), \sum_i a_i^2 \sigma_i^2\right)$$

Theorem 4.6.11 Random Vec  $X_1, X_2, \dots, X_n$  are mutually independent, if  $\exists$  functions  $g_i(x_i)$  for  $i=1, 2, \dots, n \Rightarrow$   
 $f(x_1, x_2, \dots, x_n) = g(x_1) \cdot g(x_2) \cdots g(x_n)$

Theorem 4.6.12 Let  $X_1, X_2, \dots, X_n$  be independent. Let  $g_i(x_i)$  be a function only of  $x_i, i=1, 2, \dots, n$  then the random variables  $U_i = g_i(X_i)$  are mutually independent!

Multivariate Transformations

- $A = \{x \mid f_x(x) > 0\}$
- $U_1 = g_1(X_1, X_2, \dots, X_n), U_2 = g_2(X_1, X_2, \dots, X_n), \dots, U_n = g_n(X_1, X_2, \dots, X_n)$
- Suppose  $\exists A_0, A_1, \dots, A_k$  forms a partition of  $A \Rightarrow$ 
  - $A_0$  can be empty and  $P(X \in A_0) = 0$
  - The transformation  $U_1, U_2, \dots, U_n = g_1, g_2, \dots, g_n$  is 1:1 thus the inverses can be found
- $X_1 = h_1(z), X_2 = h_2(z), \dots, X_n = h_n(z)$
- $J = \begin{vmatrix} \frac{\partial x_1}{\partial u_1} & \frac{\partial x_1}{\partial u_2} & \cdots & \frac{\partial x_1}{\partial u_n} \\ \frac{\partial x_2}{\partial u_1} & \frac{\partial x_2}{\partial u_2} & \cdots & \frac{\partial x_2}{\partial u_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x_n}{\partial u_1} & \frac{\partial x_n}{\partial u_2} & \cdots & \frac{\partial x_n}{\partial u_n} \end{vmatrix}$
- $f_Z(u_1, u_2, \dots, u_n) = \sum_i f_x(h_{1i}(u), h_{2i}(u), \dots, h_{ni}(u)) |J_i|$

Lemma 4.7.1 Let  $a$  and  $b$  be any positive numbers and let  $p$  and  $q$  be any positive numbers greater than 1 satisfying  $\frac{1}{p} + \frac{1}{q} = 1$  then

$$\frac{1}{p} a^p + \frac{1}{q} b^q \geq ab \quad (\text{equality when } a^p = b^q)$$

Theorem 4.7.2 Hölder's Inequality Let  $X$  and  $Y$  be any two RV and let  $p$  and  $q \geq 1$  with  $\frac{1}{p} + \frac{1}{q} = 1$  then

$$|E(XY)| \leq E|XY| \leq (E|X|^p)^{1/p} (E|Y|^q)^{1/q}$$

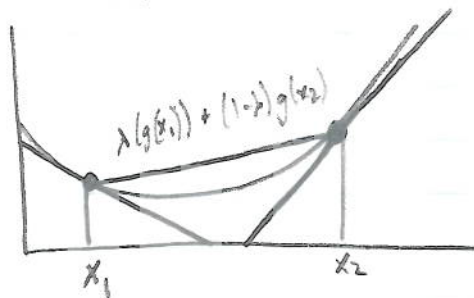
Theorem 4.7.3 Cauchy-Schwarz For any two RV  $X, Y$

$$|E(XY)| \leq E|XY| \leq (E|X|^2)^{1/2} (E|Y|^2)^{1/2}$$

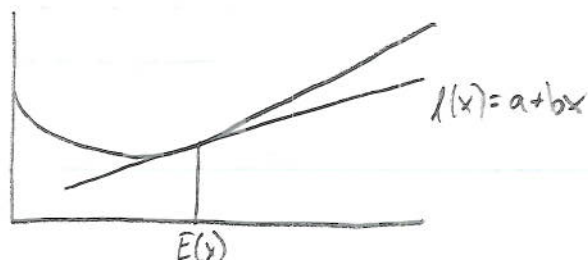
Theorem 4.7.5 Minkowski's Inequality Let  $X$  and  $Y$  be any two RV then

$$[E|X+Y|^p]^{1/p} \leq [E|X|^p]^{1/p} + [E|Y|^p]^{1/p}$$

Definition 4.7.6 • A function  $g(x)$  is convex if  $g(\lambda x + (1-\lambda)y) \leq \lambda g(x) + (1-\lambda)g(y)$   
 $\forall x$  and  $y$  and  $0 < \lambda < 1$   
 • A function  $g(x)$  is concave if  $-g(x)$  is convex



Theorem 4.7.7 Jensen's For RV  $X$   $\frac{1}{2}$   $g(x)$  is convex then  
 $E(g(X)) \geq g(E(X))$



(Equality holds when  $\forall$  line  $a+bx$  tangent to  $g(x)$   
 at  $x=E(x)$   $P(g(X)=a+bX)=1$ )

Theorem 4.7.9

- Let  $X$  be a RV
- Let  $g(x)$  and  $h(x)$  be any functions  $\Rightarrow E(g(x)), E(h(x)), E(g(x)h(x))$  exist
- a) If  $g(x)$  is a nondecreasing function and  $h(x)$  is a non increasing function then  
 $E(g(x)h(x)) \leq E(g(x)) E(h(x))$
- b) If  $g(x)$  and  $h(x)$  are both non increasing or non decreasing then  
 $E(g(x)h(x)) \geq E(g(x)) E(h(x))$

## Chapter 5

Definition 5.1.1 • The random variables  $X_1, X_2, \dots, X_n$  are called a random sample of size  $n$  from the population  $f(x)$  if  $X_1, X_2, \dots, X_n$  are mutually independent and the marginal pdf or pmf of each  $X_i$  is the same function.  
• Also denoted iid (independent and identically distributed)

Definition 5.2.1 Let  $X_1, X_2, \dots, X_n$  be a random sample of size  $n$  from a population and let  $T(X_1, X_2, \dots, X_n)$  be a real valued or vector valued function whose domain includes the sample space of  $(X_1, X_2, \dots, X_n)$  then  $Y = T(X_1, X_2, \dots, X_n)$  is called a statistic. The probability distribution of  $Y$  is the sampling distribution.

Definition 5.2.2 The sample mean,  $\bar{x} = \frac{1}{n} \sum_{i=1}^n X_i$

Definition 5.2.3 The sample variance,  $S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{x})^2$   
The sample standard deviation  $\sqrt{S^2}$

Theorem 5.2.4 Let  $X_1, X_2, \dots, X_n$  be any numbers w/  $\bar{x} = \frac{1}{n} \sum_{i=1}^n X_i$  then  
a)  $\min_a \sum_{i=1}^n (X_i - a)^2 = \sum_{i=1}^n (X_i - \bar{x})^2$   
b)  $(n-1)S^2 = \sum_{i=1}^n (X_i - \bar{x})^2 = \sum_{i=1}^n X_i^2 - n\bar{x}^2$

Lemma 5.2.5  $X_1, X_2, \dots, X_n$ , a random sample from a population and let  $g(x)$  be a function  $\ni E(g(X_i))$  and  $\text{Var}(g(X_i))$  exist then

$$\begin{aligned} 1) E\left(\sum_{i=1}^n g(X_i)\right) &= n(E(g(X_1))) \\ 2) \text{Var}\left(\sum_{i=1}^n g(X_i)\right) &= n(\text{Var } g(X_1)) \end{aligned}$$

Theorem 5.2.6 Let  $X_1, X_2, \dots, X_n$  be a random sample from a pop w/ mean  $\mu$  and variance  $\sigma^2 < \infty$  then  
a)  $E(\bar{x}) = \mu$   
b)  $\text{Var}(\bar{x}) = \sigma^2/n$   
c)  $E(s^2) = \sigma^2$

Theorem 5.2.7 Let  $X_1, X_2, \dots, X_n$  be a random sample from a population w/ MGF  $M_X(t)$  then the MGF of the sample mean is

$$M_{\bar{X}}(t) = [M_X(t/n)]^n$$

Theorem 5.2.9 If  $X$  and  $Y$  are independent continuous random variables w/ pdfs  $f_X(x)$  and  $f_Y(y)$  then the pdf of  $Z = X + Y$  is

$$f_Z(z) = \int_{-\infty}^{\infty} f_X(w) f_Y(z-w) dw$$

Theorem 5.2.11 • Suppose  $X_1, X_2, \dots, X_n$  is a random sample from a pdf or pmf  $f_X(x|\theta) = h(x)c(\theta) e^{\sum w_i(\theta)T_i(x)}$

• Define statistics  $T_1, T_2, \dots, T_k$  by

$$T_i(X_1, X_2, \dots, X_n) = \sum_{j=1}^n t_i(X_j), \quad i=1, 2, \dots, k$$

• If the set  $\{w_1(\theta), w_2(\theta), \dots, w_k(\theta)\}, \theta \in \Theta\}$  contains an open subset of  $\mathbb{R}^k$ , then the distribution of  $(T_1, T_2, \dots, T_k)$  is an exponential family of the form  $f_T(u_1, u_2, \dots, u_k|\theta) = H(u_1, u_2, \dots, u_k) [c(\theta)]^n e^{\sum w_i(\theta)u_i}$

Theorem 5.3.1 Let  $X_1, X_2, \dots, X_n$  be a random sample from a  $N(\mu, \sigma^2)$  distribution and let  $\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$  and  $S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$  Then

a)  $\bar{X}$  and  $S^2$  are independent

b)  $\bar{X} \sim N(\mu, \sigma^2/n)$

c)  $(n-1)S^2/\sigma^2 \sim \chi_{(n-1)}^2$

Lemma 5.3.2 a) If  $Z \sim N(0,1)$ , then  $Z^2 \sim \chi_{(1)}^2$

b) If  $X_1, X_2, \dots, X_n$  are independent and  $X_i \sim \chi_{p_i}^2$  then

$$X_1 + X_2 + \dots + X_n \sim \chi_{(p_1 + p_2 + \dots + p_n)}^2$$

Lemma 5.3.3 • Let  $X_j \sim N(\mu_j, \sigma_j^2)$   $j=1, 2, \dots, n$  be independent.  
for constants  $a_{ij}$  and  $b_{rj}$  ( $j=1, 2, \dots, n$ ,  $i=1, \dots, k$ ,  $r=1, \dots, m$ )

• where  $k+m \leq n$

• Define 
$$U_i = \sum_{j=1}^n a_{ij} X_j \quad i=1, 2, \dots, k$$
$$V_r = \sum_{j=1}^n b_{rj} X_j \quad r=1, 2, \dots, m$$

a) The random variables  $U_i$  and  $V_r$  are independent  
iff  $\text{Cov}(U_i, V_r) = \sum_{j=1}^n a_{ij} b_{rj} \sigma_j^2 = 0$

b) The random vectors  $(U_1, U_2, \dots, U_k)$  and  $(V_1, V_2, \dots, V_m)$   
are independent iff  $U_i \perp V_r \forall$  pairs  $i, r$  ( $i=1, 2, \dots, k; r=1, 2, \dots, m$ )

Student T  $\frac{\bar{X} - \mu}{S/\sqrt{n}} \quad f_T(t) = \frac{\Gamma(\frac{p+1}{2})}{\Gamma(\frac{p}{2})} \frac{1}{(p\pi)^{1/2}} \frac{1}{(1+t^2/p)^{(p+1)/2}} \quad -\infty < t < \infty$

Definition 5.3.4 Let  $X_1, X_2, \dots, X_n$  be a random sample from a  
 $N(\mu, \sigma^2)$  then  $\frac{\bar{X} - \mu}{S/\sqrt{n}} \sim t_{(n-1)}$

Definition 5.3.6 • For  $X_1, X_2, \dots, X_n \stackrel{iid}{\sim} N(\mu_x, \sigma_x^2) > \mu$   
 $Y_1, Y_2, \dots, Y_m \stackrel{iid}{\sim} N(\mu_y, \sigma_y^2)$

•  $F = \frac{S_x^2/\sigma_x^2}{S_y^2/\sigma_y^2} \sim F(n-1, m-1)$

•  $f_F(x) = \frac{\Gamma(\frac{p+q}{2})}{\Gamma(\frac{p}{2})\Gamma(\frac{q}{2})} \left(\frac{p}{q}\right)^{p/2} \frac{x^{(p/2)-1}}{[1+(p/q)x]^{\frac{p+q}{2}}} \quad 0 < x < \infty$

Theorem 5.3.8 a) If  $X \sim F_{p,q}$  then  $\frac{1}{X} \sim F_{q,p}$   
b) If  $X \sim t_p$  then  $X^2 \sim F_{1,p}$   
c) If  $X \sim F_{p,q}$  then  $\frac{p}{q} X \sim \text{beta}(p/2, q/2)$   
 $(1 + \frac{p}{q} X)$

Definition 5.4.1 The order statistics of  $X_1, X_2, \dots, X_n$  is the sample  
placed in ascending order  $X_{(1)}, X_{(2)}, \dots, X_{(n)}$

Theorem 5.43 • Let  $X_1, X_2, \dots, X_n$  be a random sample from a discrete distribution w/ pmf  $f_x(x_i) = p_i$  where  $x_1 < x_2 < \dots$  are the possible values of  $X$  in ascending order

• Define  $p_0 = 0$   
 $p_1 = p_1$   
 $p_2 = p_1 + p_2$   
 $\vdots$

• Let  $X_{(1)}, X_{(2)}, \dots, X_{(n)}$  be the ordered statistics then

Then

$$P(X_{(j)} \leq x_i) = \sum_{k=j}^n \binom{n}{k} p_i^k (1-p_i)^{n-k}$$

and

$$P(X_{(j)} = x_i) = \sum_{k=j}^n \binom{n}{k} [p_i^k (1-p_i)^{n-k} - p_{i-1}^k (1-p_{i-1})^{n-k}]$$

Theorem 5.44 • Let  $X_1, X_2, \dots, X_n$  be a random sample from a continuous population w/ CDF  $F_x(x)$  and pdf  $f_x(x)$

Then

$$f_{X_{(j)}}(x) = \frac{n!}{(j-1)!(n-j)!} f_x(x) [F_x(x)]^{j-1} [1-F_x(x)]^{n-j}$$

Theorem 5.46. Let  $X_{(1)}, X_{(2)}, \dots, X_{(n)}$  denote the order statistics of a random sample  $X_1, X_2, \dots, X_n$  from a continuous population w/ CDF  $F_x(x)$  and pdf  $f_x(x)$ . Then the joint pdf of  $X_{(i)}, X_{(j)}$   $1 \leq i < j \leq n$  is:

$$f_{X_{(i)}, X_{(j)}}(u, v) = \frac{n!}{(i-1)!(j-1-i)!(n-j)!} f_x(u) f_x(v) [f_x(u)]^{i-1} \\ * [F_x(v) - F_x(u)]^{j-1-i} [1-F_x(v)]^{n-j}$$

for  $-\infty < u < v < \infty$



Definition 5.5.1 A sequence of random variables  $X_1, X_2, \dots, X_n$  converges in probability to a random variable  $X$  if,  $\forall \epsilon > 0$

$$\lim_{n \rightarrow \infty} P(|X_n - X| \geq \epsilon) = 0 \text{ or, equivalently, } \lim_{n \rightarrow \infty} P(|X_n - X| < \epsilon) = 1$$

Theorem 5.5.2 Weak Law of Large Numbers (WLLN)

• Let  $X_1, X_2, \dots$  be iid random variables w/  $E(X_i) = \mu$  and  $\text{Var}(X_i) = \sigma^2 < \infty$

• Define  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$  Then  $\forall \epsilon > 0$

$$\lim_{n \rightarrow \infty} P(|\bar{X}_n - \mu| < \epsilon) = 1$$

" $\bar{X}_n$  converges in probability to  $\mu$ "

Theorem 5.5.4 Suppose that  $X_1, X_2, \dots$  converges in probability to random variable  $X$  and that  $h$  is a continuous function then  $h(X_1), h(X_2), \dots$  converges in probability to  $h(X)$ .

Definition 5.5.6 A sequence of random variables  $X_1, X_2, \dots$  converges almost surely to a random variable  $X$  if  $\forall \epsilon > 0$

$$P(\lim_{n \rightarrow \infty} |X_n - X| < \epsilon) = 1$$

Theorem 5.5.9 Strong Law of Large Numbers (SLLN)

• Let  $X_1, X_2, \dots$  be iid random variables w/  $E(X_i) = \mu$  and  $\text{Var}(X_i) = \sigma^2 < \infty$  and define  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$  then  $\forall \epsilon > 0$

$$P(\lim_{n \rightarrow \infty} |\bar{X}_n - \mu| < \epsilon) = 1$$

" $\bar{X}_n$  converges almost surely to  $\mu$ "

Definition 5.5.10 A sequence of random variables  $X_1, X_2, \dots$  converges in distribution to a random variable  $X$  if  $\lim_{n \rightarrow \infty} F_{\bar{X}_n}(x) = F_X(x)$  at all points  $x$  where  $F_X(x)$  is continuous

Theorem 5.5.12 If the sequence of random variables  $X_1, X_2, \dots$  converges in probability to a random variable  $X$ , the sequence also converges in distribution to  $X$

Theorem 5.5.13 The sequence of random variables  $X_1, X_2, \dots$  converges in probability to a constant  $\mu$  iff the sequence also converges in distribution to  $\mu$   
That is

$$\equiv P(|X_n - \mu| > \epsilon) \rightarrow 0 \quad \forall \epsilon > 0$$

$$\equiv P(X_n \leq x) \rightarrow \begin{cases} 0 & \text{if } x < \mu \\ 1 & \text{if } x > \mu \end{cases}$$

Theorem 5.5.14 (CLT) • let  $X_1, X_2, \dots$  be a sequence of iid random variables w/  $E(X_i) = \mu$  and  $0 < \text{Var}(X_i) = \sigma^2 < \infty$   
• Define  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$   
• Let  $G_n(x)$  denote the cdf of  $\sqrt{n}(\bar{X}_n - \mu)/\sigma$   
• Then  $\forall x \in \mathbb{R}$   
 $\lim_{n \rightarrow \infty} G_n(x) = \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-y^2/2} dy$   
that is,  $\frac{\sqrt{n}(\bar{X}_n - \mu)}{\sigma}$  has a limiting standard Normal dist  
 $\equiv \frac{(\bar{X}_n - \mu)}{\sigma/\sqrt{n}}$

Theorem 5.5.17 If  $X_n \rightarrow X$  in distribution and  $Y_n \rightarrow a$ , a constant, in probability then

- a)  $Y_n X_n \rightarrow aX$   
b)  $X_n + Y_n \rightarrow X + a$  } in distribution

Definition 5.5.20 If a function  $g(x)$  has derivatives of order  $r$ , that is  $g^{(r)}(x) = \frac{d^r}{dx^r} g(x)$  exists. Then for any constant  $a$ , the Taylor polynomial of order  $r$  about  $a$  is

$$T_r(x) = \sum_{i=0}^r \frac{g^{(i)}(a)}{i!} (x-a)^i$$

Theorem 5.5.21 If  $g^{(r)}(a) = \frac{d^r}{dx^r} g(x)|_{x=a}$  exists then

$$\lim_{x \rightarrow a} \frac{g(x) - T_r(x)}{(x-a)^r} = 0$$

$$\equiv g(x) - T_r(x) = \int_a^x \frac{g^{(r+1)}(t)}{r!} (x-t)^r dt$$

Theorem 5.5.24 Delta Method • Let  $Y_n$  be a sequence of random variables that satisfies

$$\sqrt{n}(Y_n - \theta) \rightarrow N(0, \sigma^2) \text{ in dist}$$

• For a given function  $g$  and a specific value of  $\theta$ , suppose that  $g'(\theta)$  exists and is not 0

• Then

$$\sqrt{n}[g(Y_n) - g(\theta)] \rightarrow N(0, \sigma^2 [g'(\theta)]^2) \text{ in dist}$$

Theorem 5.5.26 2<sup>nd</sup> Order Delta Method • Let  $Y_n$  be a sequence of RV

that satisfies  $\sqrt{n}(Y_n - \theta) \rightarrow N(0, \sigma^2)$  in dist

• For a given function  $g$  and a specific value of  $\theta$ , suppose that  $g'(\theta) = 0$  exists and  $g''(\theta)$  exists and is not 0 then

$$n[g(Y_n) - g(\theta)] \rightarrow \sigma^2 \frac{g''(\theta)}{2} \chi_{(1)}^2 \text{ in dist}$$

Theorem 5.5.28 Let  $X_1, X_2, \dots, X_n$  be a random sample w/  
 $E(X_{ij}) = \mu_i$  and  $\text{Cov}(X_{ix}, X_{jx}) = \sigma_{ij}$ . For a given  
function  $g$  with continuous 1<sup>st</sup> partial derivatives  
and a specific value of  $\mu = (\mu_1, \mu_2, \dots, \mu_p)$  for  
which

$$T^2 = \sum \sum \sigma_{ij} \frac{\partial g(\mu)}{\partial \mu_i} \frac{\partial g(\mu)}{\partial \mu_j} > 0$$

Then

$$\sqrt{n} [g(\bar{X}_1, \bar{X}_2, \dots, \bar{X}_s) - g(\mu_1, \mu_2, \dots, \mu_p)] \rightarrow N(0, T^2) \text{ in dist}$$

## Chapter 6

Definition 6.2.1 A statistic  $T(X)$  is a sufficient statistic for  $\Theta$  if the conditional distribution of the sample  $X$  given the value of  $T(X)$  does not depend on  $\Theta$

Theorem 6.2.2. If  $p(x|\theta)$  is the joint pdf or pmf of  $X$  and  $g(t|\theta)$  is the pdf or pmf of  $T(X)$  then  $T(X)$  is a sufficient for  $\Theta$  if  $\forall x$  in the sample space, the ratio  $\frac{p(x|\theta)}{g(T(x)|\theta)}$  is constant as a function of  $\theta$ .

Theorem 6.2.6 Factorization Theorem - Let  $f(x|\theta)$  denote the joint pdf or pmf of a sample  $X$ . A statistic  $T(X)$  is a sufficient statistic for  $\Theta$  iff there exist functions  $g(t|\theta)$  and  $h(x)$   $\ni \forall$  sample points  $x$  and all parameter points  $\theta$

$$f(x|\theta) = g(T(x)|\theta)h(x)$$

Theorem 6.2.10 Let  $X_1, X_2, \dots, X_n$  be iid observations from a pdf or pmf  $f(x|\theta)$  that belongs to an exponential family

$$f(x|\theta) = h(x)c(\theta) e^{\sum_{i=1}^k \eta_i(\theta) t_i(x)} \quad \text{where } \theta = (\theta_1, \theta_2, \dots, \theta_k), \quad k < \infty$$

Then

$$T(X) = \left( \sum_{i=1}^n t_1(X_i), \sum_{i=1}^n t_2(X_i), \dots, \sum_{i=1}^n t_k(X_i) \right) \text{ is sufficient for } \theta$$

Definition 6.2.11 A sufficient statistic  $T(X)$  is called a minimal sufficient statistic if for any other sufficient statistic  $T'(X)$ ,  $T(X)$  is a function of  $T'(X)$

Theorem 6.2.13 Let  $f(x|\theta)$  be the pmf or pdf of a sample  $X$ . Suppose there exists a function  $T(x)$   $\ni \forall$  two sample points  $x$  and  $y$ , the ratio  $f(x|\theta)/f(y|\theta)$  is constant as a function of  $\theta$  iff  $T(x) = T(y)$ . Then  $T(X)$  is a minimal sufficient for  $\Theta$

Definition 6.2.16 A statistic  $S(X)$  whose distribution does not depend on the parameter  $\theta$  is called an ancillary statistic

Definition 6.2.21 Let  $f(t|\theta)$  be a family of pdfs or pmfs for a statistic  $T(X)$ . The family of probability distributions is called complete if  $E_{\theta}(g(T)) = 0 \forall \theta$  implies  $P_{\theta}(g(T) = 0) = 1 \forall \theta$ . Equivalently,  $T(X)$  is called a complete statistic

Theorem 6.2.24 (Basu's Theorem) If  $T(X)$  is a complete and minimal sufficient statistic, then  $T(X)$  is independent of every ancillary statistic

Theorem 6.2.25 The statistic defined in 6.2.10 is also complete if  $\{w_1(\theta), w_2(\theta), \dots, w_k(\theta) \mid \theta \in \Theta\}$  contains an open set in  $\mathbb{R}^k$

Theorem 6.2.28 If a minimal sufficient statistic exists, then any complete statistic is also a minimal statistic

Skipped 6.3.1 & 6.4

## Chapter 7

Definition 7.1.1 A point estimator is any function  $W(X_1, X_2, \dots, X_n)$  of a sample, that is, any statistic is a point estimator

### Method of Moments

Define:

$$\begin{aligned} m_1 &= \frac{1}{n} \sum x_i & \mu'_1 &= E(X) \\ m_2 &= \frac{1}{n} \sum x_i^2 & \mu'_2 &= E(X^2) \\ & \vdots & & \vdots \\ m_k &= \frac{1}{n} \sum x_i^k & \mu'_k &= E(X^k) \end{aligned}$$

Solve the system

$$\begin{aligned} m_1 &= \mu'_1 \\ m_2 &= \mu'_2 \\ & \vdots \\ m_k &= \mu'_k \end{aligned}$$

### Maximum Likelihood Estimator

$$X_1, X_2, \dots, X_n \sim f(x | \theta_1, \theta_2, \dots, \theta_k)$$

$$L(\theta | x) = \prod f(x_i | \theta)$$

Def 7.2.4 MLE =  $\hat{\theta}$  = parameter which  $L(\theta | x)$  attains its maximum found using the calculus

Theorem 7.2.10 Invariance property of MLE if  $\hat{\theta}$  is the MLE of  $\theta$ , then for any function  $T(\theta)$  the MLE of  $T(\theta)$  is  $T(\hat{\theta})$

### Bayesian Estimators

- $X_1, X_2, \dots, X_n$  is drawn from a population indexed by  $\theta$
- Prior distribution,  $\pi(\theta)$ , is the distribution of  $\theta$  based on 'prior' beliefs or intuition
- Posterior,  $\pi(\theta | x)$ , is the updated prior when we see  $X_1, X_2, \dots, X_n$

$$\pi(\theta | x) = \frac{f(x | \theta) \pi(\theta)}{\int f(x | \theta) \pi(\theta) d\theta}$$

Definition 7.2.5 Let  $\mathcal{F}$  denote the class of pdfs or pmfs  $f(x|\theta)$  indexed by  $\theta$ . A class  $\Pi$  of prior distributions is a conjugate family for  $\mathcal{F}$  if the posterior distribution is in the class  $\Pi \forall f \in \mathcal{F}$ , all priors in  $\Pi$  and all  $x \in \mathcal{X}$   
 ie: If we start with a beta prior we will end up w/ a beta posterior

7.2.4 omitted

Definition 7.3.1 The mean square error (MSE) of an estimator  $W$  of a parameter  $\theta$  is  $E_{\theta}(W-\theta)^2$

Definition 7.3.2 The bias of a point estimator  $W$  of a parameter  $\theta$  is the difference between the expected value of  $W$  and  $\theta$

$$\text{Bias} = E(W) - \theta$$

Note: if Bias = 0  $\rightarrow$  the estimator  $W$  is unbiased  
 $\rightarrow \text{MSE} = E_{\theta}(W-\theta)^2 = \text{Var}_{\theta}(W)$

Definition 7.3.7 'An estimator  $W^*$  is a best unbiased estimator of  $\tau(\theta)$  if it satisfies  $E_{\theta}(W^*) = \tau(\theta) \forall \theta$  and, for any other estimator  $W'$  w/  $E_{\theta}(W') = \tau(\theta) \forall \theta$  we have  $\text{Var}_{\theta}(W^*) \leq \text{Var}_{\theta}(W')$   
 'Also called the uniform minimum variance unbiased estimator of  $\tau(\theta)$  (UMVUE)

Theorem 7.3.9 Let  $X_1, X_2, \dots, X_n$  be a sample w/ pdf  $f(x|\theta)$  and let  $W(X) = W(X_1, X_2, \dots, X_n)$  be any estimator satisfying  
 $\frac{d}{d\theta} E_{\theta}(W(X)) = \int \frac{\partial}{\partial \theta} [W(x)f(x|\theta)] dx$  and  $\text{var}(W(X)) < \infty$

Then

$$\text{Var}_{\theta}(W(X)) \geq \frac{\left(\frac{d}{d\theta} E_{\theta}(W(X))\right)^2}{E_{\theta}\left(\left(\frac{\partial}{\partial \theta} \ln f(X|\theta)\right)^2\right)}$$

Cramér Rao Lower Bound



Corollary 7.3.10 When  $X_1, X_2, \dots, X_n$  are iid theorem 7.3.9 becomes

$$\text{Var}_\theta(W(X)) \geq \frac{\left(\frac{\partial}{\partial \theta} E_\theta W(X)\right)^2}{n E_\theta \left(\left(\frac{\partial}{\partial \theta} \ln f(X|\theta)\right)^2\right)}$$

Lemma 7.3.11 If  $f(x|\theta)$  satisfies  $\frac{\partial}{\partial \theta} E_\theta \left(\frac{\partial}{\partial \theta} \ln f(x|\theta)\right) = \int \frac{\partial}{\partial \theta} \left[\frac{\partial}{\partial \theta} \ln f(x|\theta)\right] f(x|\theta) dx$   
(Always true for exponential families)

then

$$E_\theta \left(\left(\frac{\partial}{\partial \theta} \log f(x|\theta)\right)^2\right) = -E_\theta \left(\frac{\partial^2}{\partial \theta^2} \ln f(x|\theta)\right)$$

\* This result can, very usefully, be applied to Theorem 7.3.9 or Corollary 7.3.10

Corollary 7.3.15 Let  $X_1, X_2, \dots, X_n$  be iid  $f(x|\theta)$  where  $f(x|\theta)$  satisfies the conditions of theorem 7.3.9. If  $W$  is an unbiased estimator of  $\tau(\theta)$  then  $W(X)$  attains the CRLB iff

$$\frac{\partial}{\partial \theta} \ln(L(\theta; X)) = a(\theta) [W(X) - \tau(\theta)] \text{ for some function } a(\theta)$$

Theorem 7.3.17 Rao-Blackwell Let  $W$  be any unbiased estimator of  $\tau(\theta)$  and let  $T$  be a sufficient statistic for  $\theta$ .

• Define  $\phi(T) = E(W|T)$

• Then  $E_\theta(\phi(T)) = \tau(\theta)$  and  $\text{Var}_\theta(\phi(T)) \leq \text{Var}_\theta(W) \forall \theta$

→  $\phi(T)$  is a uniformly better unbiased estimator of  $\tau(\theta)$

Theorem 7.3.19 If  $W$  is a best unbiased estimator of  $\tau(\theta)$  then  $W$  is unique

Theorem 7.3.20 If  $E_\theta(W) = \tau(\theta)$ ,  $W$  is the best unbiased estimator of  $\tau(\theta)$  iff  $W$  is uncorrelated with all unbiased estimators of 0

Theorem 7.3.23 Let  $T$  be a complete sufficient statistic for a parameter  $\theta$  and let  $\phi(T)$  be any estimator based only on  $T$ . Then  $\phi(T)$  is the unique best unbiased estimator of its expected value

7.3.4 omitted

## Chapter 8

Definition 8.1.1 A hypothesis is a statement about a population parameter

Definition 8.1.2 The two complementary hypotheses in a hypothesis test are called the null hypothesis and the alternative hypothesis

Definition 8.1.3 A hypothesis testing procedure or hypothesis test is a rule that specifies

i: For which sample values the decision is made to accept  $H_0$  as true

The subset of the sample space for which  $H_0$  will be rejected is called the rejection region. The complement is called the acceptance region

Definition 8.2.1 The likelihood ratio test statistic for testing  $H_0: \theta \in \Theta_0$  is  $H_1: \theta \in \Theta^c$

$$\lambda(\underline{x}) = \frac{\sup_{\Theta_0} L(\theta|\underline{x})}{\sup_{\Theta} L(\theta|\underline{x})} = \frac{L(\hat{\Theta}_0|\underline{x})}{L(\hat{\Theta}|\underline{x})} \quad \begin{array}{l} \hat{\Theta}_0 \text{ is the } \text{Restricted MLE} \\ \hat{\Theta} \text{ is the } \text{unrestricted MLE} \end{array}$$

A likelihood ratio test gives the rejection region  $R = \{ \underline{x} \mid \lambda(\underline{x}) \leq c \}$  where  $0 \leq c \leq 1$

Theorem 8.2.4 If  $T(\underline{X})$  is a sufficient statistic for  $\theta$  and  $\lambda^*(t)$  and  $\lambda(\underline{x})$  are the LRT statistics based on  $T$  and  $\underline{X}$  respectively then  $\lambda^*(T(\underline{x})) = \lambda(\underline{x}) \quad \forall \underline{x}$  in the sample space

Bayesian Tests 1)  $P(\theta \in \Theta_0 | X) = P(H_0 \text{ is true})$   
 2)  $P(\theta \in \Theta_0^c | X) = P(H_1 \text{ is true})$

B.2.3 omitted

Table 8.3.1

		Decision	
		Fail to reject $H_0$	Reject $H_0$
Truth	$H_0$	Correct	Type I error
	$H_1$	Type II error	Correct

Definition 8.3.1 Power function of a hypothesis test w/ rejection region  $R$  is the function of  $\theta$  defined by  $\beta(\theta) = P_\theta(X \in R)$   
 \* we want  $\beta(\theta)$  close to zero  $\forall \theta \in \Theta_0$   
 close to one  $\forall \theta \in \Theta_0^c$

Definition 8.3.5 For  $0 \leq \alpha \leq 1$ , a test w/ power function  $\beta(\theta)$  is a size  $\alpha$  test if  $\sup_{\theta \in \Theta_0} \beta(\theta) = \alpha$

Definition 8.3.6 For  $0 \leq \alpha \leq 1$ , a test w/ power function  $\beta(\theta)$  is a level  $\alpha$  test if  $\sup_{\theta \in \Theta_0} \beta(\theta) \leq \alpha$

Definition 8.3.9 A test w/ power function  $\beta(\theta)$  is unbiased if  $\beta(\theta') \geq \beta(\theta'')$  for every  $\theta' \in \Theta_0^c$  and  $\theta'' \in \Theta_0$

Definition 8.3.11 Let  $\mathcal{L}$  be a class of tests for testing  $H_0: \theta \in \Theta_0$  vs  $H_1: \theta \in \Theta_0^c$ . A test in class  $\mathcal{L}$ , w/ power function  $\beta(\theta)$  is a uniformly most powerful test if  $\beta(\theta) \geq \beta'(\theta) \forall \theta \in \Theta_0^c$  and every  $\beta'(\theta)$  that is a power function of a test in class  $\mathcal{L}$

Theorem 8.3.12 Neyman-Pearson Lemma Consider testing  $H_0: \theta = \theta_0$  versus  $H_1: \theta = \theta_1$  where the pdf or pmf corresponding to  $\theta_i$  is  $f(x|\theta_i)$   $i=0,1$  using a test w/ rejection region  $R$  that satisfies

$$x \in R \text{ if } f(x|\theta_1) \geq k f(x|\theta_0)$$

① and

$$x \in R^c \text{ if } f(x|\theta_1) < k f(x|\theta_0)$$

② for some  $k \geq 0$  and

$$\alpha = P_{\theta_0}(X \in R)$$

Then

a.) Any test that satisfies ① and ② is a UMP level  $\alpha$  test

b.) If  $\exists$  a test satisfying ① and ② w/  $k > 0$ , then every UMP level  $\alpha$  test is a size  $\alpha$  test and every UMP level  $\alpha$  test satisfies ① except perhaps on a set  $A$  satisfying  $P_{\theta_0}(X \in A) = P_{\theta_1}(X \in A) = 0$

Corollary 8.3.13 Consider testing  $H_0: \theta = \theta_0$  versus  $H_1: \theta = \theta_1$   
 • Suppose  $T(X)$  is a sufficient statistic for  $\theta$  and  $g(t|\theta_i)$  is the pdf or pmf of  $T$  corresponding to  $\theta_i$   $i=0,1$ .  
 • Then any test based on  $T$  w/ rejection region  $S$  is a UMP level  $\alpha$  test if it satisfies

$$t \in S \text{ if } g(t|\theta_1) \geq k g(t|\theta_0)$$

and

$$t \in S^c \text{ if } g(t|\theta_1) < k g(t|\theta_0)$$

for some  $k \geq 0$  where

$$\alpha = P_{\theta_0}(T \in S)$$

Definition 8.3.16 A family of pdfs or pmfs  $\{g(t|\theta) | \theta \in \Theta\}$  for a univariate random variable  $T$  w/ real-valued parameter  $\theta$  has a monotone likelihood ratio (MLR) if for every  $\theta_2 > \theta_1$ ,  $g(t|\theta_2)/g(t|\theta_1)$  is a monotone (nonincreasing or nondecreasing) function of  $t$  on  $\{t | g(t|\theta_1) > 0 \text{ or } g(t|\theta_2) > 0\}$

Theorem 8.3.17 Karlin Rubin Consider testing  $H_0: \theta \leq \theta_0$   
 $H_1: \theta > \theta_0$

Suppose that  $T$  is a sufficient statistic for  $\theta$  and the family of pdfs or pmfs  $\{g(t|\theta) | \theta \in \Theta\}$  of  $T$  has a MLR. Then for any  $t_0$ , the test that rejects  $H_0$  iff  $T > t_0$  is a UMP level  $\alpha$  test where  $\alpha = P_{\theta_0}(T > t_0)$

## Chapter 9

Definition 9.11 An interval estimate of  $\theta$  is any interval estimator  $[L(x), U(x)]$  making the inference  $L(x) < \theta < U(x)$

Definition 9.14 Coverage Probability =  $P_\theta(\theta \in [L(x), U(x)])$

Definition 9.15 Confident Coefficient =  $\inf_{\theta} P_\theta(\theta \in [L(x), U(x)])$

Theorem 9.22 i)  $\forall \theta_0 \in \Theta$ , let  $A(\theta_0)$  = the acceptance region of a level  $\alpha$  test of  $H_0: \theta = \theta_0$   
 $\forall x \in X$  define  $C(x) = \{\theta_0 \mid x \in A(\theta_0)\}$   
then  $C(x)$  is a  $1-\alpha$  confidence set  
ii) If  $C(x)$  is a  $1-\alpha$  confidence set  
 $\forall \theta_0 \in \Theta$   $A(\theta_0) = \{x \mid \theta_0 \in C(x)\}$  is the acceptance region of a level  $\alpha$  test of  $H_0: \theta = \theta_0$   
proof 9.22

Definition 9.26 A random variable  $Q(x, \theta)$  is a pivotal quantity or pivot if  $Q(x, \theta)$  is independent of all parameters

PIVOT RULE If  $T \sim f(t|\theta)$  can be expressed as

$$f(t|\theta) = g(Q(t, \theta)) \left| \frac{\partial}{\partial t} Q(t, \theta) \right|$$

then  $Q(t, \theta)$  is a pivot

$$\text{thus } C(x) = \{\theta_0 \mid a \leq Q(x, \theta_0) \leq b\}$$

① If  $Q(t, \theta)$  is an inc. function of  $\theta$

$$L(x, a) \leq \theta \leq U(x, b)$$

② If  $Q(t, \theta)$  is a dec. function of  $\theta$

$$L(x, b) \leq \theta \leq U(x, a)$$

Theorem 9.2.12

- Let  $T$  be a statistic w/ continuous  $F_T(t|\theta)$
- Let  $\alpha_1 + \alpha_2 = \alpha$
- $\forall t \in \mathcal{T}$ 
  - IF  $F_T(t|\theta)$  is a dec function of  $\theta$   
 $F_T(t|\theta_u(t)) = \alpha_1$ ,  $F_T(t|\theta_L(t)) = 1 - \alpha_2$
  - IF  $F_T(t|\theta)$  is an inc. function of  $\theta$   
 $F_T(t|\theta_u(t)) = 1 - \alpha_2$ ,  $F_T(t|\theta_L(t)) = \alpha_1$

Then  $(\theta_L(t), \theta_u(t))$  is a  $1 - \alpha$  CI  
Proof 432

Theorem 9.2.14

- Let  $T$  be a discrete statistic w/ CDF  $F_T(t|\theta)$
- Let  $\alpha_1 + \alpha_2 = \alpha$
- $\forall t \in \mathcal{T}$ 
  - IF  $F_T(t|\theta)$  is a dec function of  $\theta$   
 $P(T \leq t | \theta_u(t)) = \alpha_1$ ,  $P(T \geq t | \theta_L(t)) = \alpha_2$
  - IF  $F_T(t|\theta)$  is an inc. function of  $\theta$   
 $P(T \geq t | \theta_u(t)) = \alpha_1$ ,  $P(T \leq t | \theta_L(t)) = \alpha_2$

Then  $(\theta_L(t), \theta_u(t))$  is a  $1 - \alpha$  CI  
Proof 434

Credible Set With  $\pi(\theta|x)$ , the posterior of  $\theta$  given  $x$  then for any set  $A \subset \Theta$  the Credible Prb. of  $A$  is  
 $\int_A \pi(\theta|x) d\theta = P(\theta \in A|x)$

Theorem 9.3.2 Let  $f(x)$  be a unimodal pdf. If  $[a, b]$  satisfies

- $\int_a^b f(x) dx = 1 - \alpha$
- $f(a) = f(b) > 0$  and
- $a \leq x^* \leq b$  where  $x^*$  is a mode of  $f(x)$

Then  $[a, b]$  is the shortest interval among all that satisfy:  
proof: p442