

Web-based Supplementary Materials for “Latent-model Robustness in Joint Models for a Primary Endpoint and a Longitudinal Process”

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Web Appendix A: Proof of Theorem 1

For brevity, the subject index i is dropped in the following argument. Recall in Theorem 1, $\mathbf{S} = (\mathbf{D}^T \mathbf{D})^{-1} \mathbf{D}^T \mathbf{W}_{m \times 1}$, which is the ordinary least squares estimator for \mathbf{X} if one treats \mathbf{X} as a parameter. Assuming σ^2 known and viewing \mathbf{X} as an unknown parameter, \mathbf{S} is a complete sufficient statistic for \mathbf{X} , and $\mathbf{S} | \mathbf{X} \sim N_p\{\mathbf{X}, \sigma^2(\mathbf{D}^T \mathbf{D})^{-1}\}$. Therefore, by the Factorization Theorem,

$$f_{\mathbf{W} | \mathbf{X}}(\mathbf{w} | \mathbf{x}; \sigma^2) = f_{\mathbf{W} | \mathbf{S}}(\mathbf{w} | \mathbf{s}; \sigma^2) f_{\mathbf{S} | \mathbf{X}}(\mathbf{s} | \mathbf{x}; \sigma^2),$$

where $f_{\mathbf{W} | \mathbf{S}}(\mathbf{w} | \mathbf{s}; \sigma^2)$ is free of \mathbf{x} ; and $f_{\mathbf{S} | \mathbf{X}}(\mathbf{s} | \mathbf{x}; \sigma^2) = |\mathbf{G}|^{-1} \phi\{\mathbf{G}^{-1}(\mathbf{s} - \mathbf{x})\}$, $\phi(\cdot)$ is the density of the p -dimensional standard normal density, with $\mathbf{G} \mathbf{G}^T = \sigma^2(\mathbf{D}^T \mathbf{D})^{-1}$. It follows that the observed data density in equation (2) in the article can be rewritten as

$$\begin{aligned} f_{\mathbf{Y}, \mathbf{W} | \mathbf{H}}(\mathbf{y}, \mathbf{w} | \mathbf{h}; \Omega) &= \int f_{\mathbf{Y} | \mathbf{X}, \mathbf{H}}(\mathbf{y} | \mathbf{x}, \mathbf{h}; \boldsymbol{\theta}, \boldsymbol{\zeta}) f_{\mathbf{W} | \mathbf{X}}(\mathbf{w} | \mathbf{x}; \sigma^2) f_{\mathbf{X} | \mathbf{H}}^{(a)}(\mathbf{x} | \mathbf{h}; \boldsymbol{\tau}^{(a)}) d\mathbf{x} \\ &= f_{\mathbf{W} | \mathbf{S}}(\mathbf{w} | \mathbf{s}; \sigma^2) \times \\ &\quad \int f_{\mathbf{Y} | \mathbf{X}, \mathbf{H}}(\mathbf{y} | \mathbf{x}, \mathbf{h}; \boldsymbol{\theta}, \boldsymbol{\zeta}) f_{\mathbf{S} | \mathbf{X}}(\mathbf{s} | \mathbf{x}; \sigma^2) f_{\mathbf{X} | \mathbf{H}}^{(a)}(\mathbf{x} | \mathbf{h}; \boldsymbol{\tau}^{(a)}) d\mathbf{x}. \end{aligned} \quad (\text{A.1})$$

Next consider the integral in expression (A.1), and specifically the difference

$$\begin{aligned} \tilde{\Delta} &= \int f_{\mathbf{Y} | \mathbf{X}, \mathbf{H}}(\mathbf{y} | \mathbf{x}, \mathbf{h}; \boldsymbol{\theta}, \boldsymbol{\zeta}) f_{\mathbf{S} | \mathbf{X}}(\mathbf{s} | \mathbf{x}; \sigma^2) f_{\mathbf{X} | \mathbf{H}}^{(a)}(\mathbf{x} | \mathbf{h}; \boldsymbol{\tau}^{(a)}) d\mathbf{x} \\ &\quad - f_{\mathbf{Y} | \mathbf{S}, \mathbf{H}}(\mathbf{y} | \mathbf{s}, \mathbf{h}; \boldsymbol{\theta}, \boldsymbol{\zeta}) f_{\mathbf{X} | \mathbf{H}}^{(a)}(\mathbf{s} | \mathbf{h}; \boldsymbol{\tau}^{(a)}). \end{aligned}$$

After the change of variable $\mathbf{z} = \mathbf{G}^{-1}(\mathbf{x} - \mathbf{s})$ and rearrangement of terms, we find that

$$\begin{aligned} \tilde{\Delta} = \int \left\{ f_{\mathbf{Y}|\mathbf{X},\mathbf{H}}(\mathbf{y}|\mathbf{s} + \mathbf{G}\mathbf{z}, \mathbf{h}; \boldsymbol{\theta}, \zeta) f_{\mathbf{X}|\mathbf{H}}^{(a)}(\mathbf{s} + \mathbf{G}\mathbf{z}|\mathbf{h}; \boldsymbol{\tau}^{(a)}) - \right. \\ \left. f_{\mathbf{Y}|\mathbf{S},\mathbf{H}}(\mathbf{y}|\mathbf{s}, \mathbf{h}; \boldsymbol{\theta}, \zeta) f_{\mathbf{X}|\mathbf{H}}^{(a)}(\mathbf{s}|\mathbf{h}; \boldsymbol{\tau}^{(a)}) \right\} \phi(\mathbf{z}) d\mathbf{z}. \end{aligned} \quad (\text{A.2})$$

We formalize the condition that the longitudinal process information increases by assuming that the minimum eigenvalue of $\mathbf{D}^T \mathbf{D}$ diverges to $+\infty$. In this case, $\mathbf{G} \rightarrow \mathbf{0}_{p \times p}$, and the integrand in (A.2) converges to zero. Thus, as the longitudinal process information increases without bound, $\tilde{\Delta} \rightarrow 0$ whenever integration and limit can be interchanged in (A.2). A sufficient condition for the interchange of limit and integration is that

$$|f_{\mathbf{Y}|\mathbf{X},\mathbf{H}}(\mathbf{y}|\mathbf{x}, \mathbf{h}; \boldsymbol{\theta}, \zeta) f_{\mathbf{X}|\mathbf{H}}^{(a)}(\mathbf{x}|\mathbf{h}; \boldsymbol{\tau}^{(a)})| \leq M$$

for some positive constant M at each fixed \mathbf{y} , as then the integrand in (A.2) is bounded by an integrable function, $2M\phi(\mathbf{z})$, and the result follows via the Lebesgue Dominated Convergence Theorem. Finally, note that as $\tilde{\Delta} \rightarrow 0$, the ratio of the expressions

$$f_{\mathbf{W}|\mathbf{S}}(\mathbf{w}|\mathbf{s}; \sigma^2) \int f_{\mathbf{Y}|\mathbf{X},\mathbf{H}}(\mathbf{y}|\mathbf{x}, \mathbf{h}; \boldsymbol{\theta}, \zeta) f_{\mathbf{S}|\mathbf{X}}(\mathbf{s}|\mathbf{x}; \sigma^2) f_{\mathbf{X}|\mathbf{H}}^{(a)}(\mathbf{x}|\mathbf{h}; \boldsymbol{\tau}^{(a)}) d\mathbf{x}, \quad (\text{A.3})$$

$$f_{\mathbf{W}|\mathbf{S}}(\mathbf{w}|\mathbf{s}; \sigma^2) f_{\mathbf{Y}|\mathbf{S},\mathbf{H}}(\mathbf{y}|\mathbf{s}, \mathbf{h}; \boldsymbol{\theta}, \zeta) f_{\mathbf{X}|\mathbf{H}}^{(a)}(\mathbf{s}|\mathbf{h}; \boldsymbol{\tau}^{(a)}), \quad (\text{A.4})$$

approaches one. Therefore, the ratio of the density in (2), re-expressed in (A.3), over (A.4) also approaches one as the longitudinal process information increases.

Web Appendix B: Derivations of Variance Estimators $\hat{\nu}_1$ and $\hat{\nu}_2$

Notations:

- For $i = 1, \dots, n$, \mathbf{Q}_i is the observed data for subject i ; $\mathbf{Q}_i^{(B)}$ is the B sets of λ -remeasured data for subject i . $\mathbf{Q} = \{\mathbf{Q}_i, i = 1, \dots, n\}$; $\mathbf{Q}^{(B)} = \{\mathbf{Q}_i^{(B)}, i = 1, \dots, n\}$.
- $\boldsymbol{\Omega}$ denotes the $d \times 1$ vector of all unknown parameters in the joint model.
 $\boldsymbol{\Omega}_{-\sigma^2}$ denotes $\boldsymbol{\Omega}$ excluding σ^2 .

- $E[\boldsymbol{\psi}\{\mathbf{Q}_i; \boldsymbol{\Omega}_{-\sigma^2}(0), \sigma^2(0)\}] = \mathbf{0}$ uniquely defines $\boldsymbol{\Omega}(0) = \{\boldsymbol{\Omega}_{-\sigma^2}(0)^T, \sigma^2(0)\}^T$;
 $E[\boldsymbol{\psi}^{(B)}\{\mathbf{Q}_i^{(B)}; \boldsymbol{\Omega}_{-\sigma^2}(\lambda), \sigma^2(\lambda)\}] = \mathbf{0}$ uniquely defines $\boldsymbol{\Omega}(\lambda) = \{\boldsymbol{\Omega}_{-\sigma^2}(\lambda)^T, \sigma^2(\lambda)\}^T$ for $\lambda > 0$, where the expectations are with respect to the true densities of \mathbf{Q}_i and $\mathbf{Q}_i^{(B)}$, respectively, $\sigma^2(\lambda) = (1 + \lambda)\sigma^2(0)$, and $\boldsymbol{\psi}^{(B)}\{\mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}\} = B^{-1} \sum_{b=1}^B \boldsymbol{\psi}\{\mathbf{Q}_{b,i}(\lambda); \boldsymbol{\Omega}\}$.
- $\tilde{\boldsymbol{\Omega}}(0)$ solves $\sum_{i=1}^n \boldsymbol{\psi}(\mathbf{Q}_i; \boldsymbol{\Omega}) = \mathbf{0}$; $\tilde{\boldsymbol{\Omega}}_B(\lambda)$ solves $\sum_{i=1}^n \boldsymbol{\psi}^{(B)}\{\mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}\} = \mathbf{0}$.
- $t_1^*(\lambda) = [\mathbf{T}_1(\lambda)]_{(k)}[\hat{\boldsymbol{\nu}}_1]_{(k)}^{-1/2}$, where $\mathbf{T}_1(\lambda) = n^{1/2} \left\{ \tilde{\boldsymbol{\Omega}}_{-\sigma^2}(\lambda) - \tilde{\boldsymbol{\Omega}}_{-\sigma^2}(0) \right\}$.
- $t_2^*(\lambda) = [\mathbf{T}_2(\lambda)]_{(k)}[\hat{\boldsymbol{\nu}}_2]_{(k)}^{-1/2}$, where $\mathbf{T}_2(\lambda) = n^{-1/2} \sum_{i=1}^n \boldsymbol{\psi}^{(B)}\left\{ \mathbf{Q}_i^{(B)}(\lambda); \tilde{\boldsymbol{\Omega}}_{-\sigma^2}(0), (1 + \lambda)\tilde{\sigma}^2(0) \right\}$.
- For a positive definite matrix $\boldsymbol{\Pi}$, define $\boldsymbol{\Pi}^{1/2}$ as the positive definite square root such that $\boldsymbol{\Pi}^{1/2}(\boldsymbol{\Pi}^{1/2})^T = \boldsymbol{\Pi}$, and $\boldsymbol{\Pi}^{-1/2}$ as the inverse of $\boldsymbol{\Pi}^{1/2}$. Define $\mathbf{T}_1^* = \hat{\boldsymbol{\nu}}_1^{-1/2} \mathbf{T}_1(\lambda)$ and $\mathbf{T}_2^* = \hat{\boldsymbol{\nu}}_2^{-1/2} \mathbf{T}_2(\lambda)$.
- Consider the null hypothesis, $H_0 : \boldsymbol{\Omega}_{-\sigma^2}(\lambda) - \boldsymbol{\Omega}_{-\sigma^2}(0) = \mathbf{0}$, and the contiguous alternative hypothesis, $H_a : \boldsymbol{\Omega}_{-\sigma^2}(\lambda) - \boldsymbol{\Omega}_{-\sigma^2}(0) = n^{-1/2} \boldsymbol{\Delta}^*(\lambda)$.

Define the following Hessian matrices and the associated empirical estimators.

$$\begin{aligned} \mathbf{A}_1\{\boldsymbol{\Omega}(0)\} &= E\left\{-\partial\boldsymbol{\psi}(\mathbf{Q}_i; \boldsymbol{\Omega})/\partial\boldsymbol{\Omega}^T\right\} \Big|_{\boldsymbol{\Omega} = \boldsymbol{\Omega}(0)}; \\ \hat{\mathbf{A}}_1\{\mathbf{Q}; \tilde{\boldsymbol{\Omega}}(0)\} &= -n^{-1} \sum_{i=1}^n \partial\boldsymbol{\psi}(\mathbf{Q}_i; \boldsymbol{\Omega})/\partial\boldsymbol{\Omega}^T \Big|_{\boldsymbol{\Omega} = \tilde{\boldsymbol{\Omega}}(0)}; \\ \mathbf{A}_2\{\boldsymbol{\Omega}(\lambda)\} &= E\left[-\partial\boldsymbol{\psi}^{(B)}\{\mathbf{Q}_i^{(B)}; \boldsymbol{\Omega}\}/\partial\boldsymbol{\Omega}^T\right] \Big|_{\boldsymbol{\Omega} = \boldsymbol{\Omega}(\lambda)}; \\ \hat{\mathbf{A}}_2\{\mathbf{Q}^{(B)}(\lambda); \tilde{\boldsymbol{\Omega}}(\lambda)\} &= -n^{-1} \sum_{i=1}^n \partial\boldsymbol{\psi}^{(B)}\{\mathbf{Q}_i^{(B)}; \boldsymbol{\Omega}\}/\partial\boldsymbol{\Omega}^T \Big|_{\boldsymbol{\Omega} = \tilde{\boldsymbol{\Omega}}(\lambda)}. \end{aligned}$$

Similarly denote by $\mathbf{A}_2\{\boldsymbol{\Omega}_{-\sigma^2}(0), (1 + \lambda)\sigma^2(0)\}$ the expectation $E[-\partial\boldsymbol{\psi}^{(B)}\{\mathbf{Q}_i^{(B)}; \boldsymbol{\Omega}\}/\partial\boldsymbol{\Omega}^T]$ evaluated at $\boldsymbol{\Omega} = \{\boldsymbol{\Omega}_{-\sigma^2}(0)^T, (1 + \lambda)\sigma^2(0)\}^T$. And define $\hat{\mathbf{A}}_2\{\mathbf{Q}^{(B)}(\lambda); \tilde{\boldsymbol{\Omega}}_{-\sigma^2}(0), (1 + \lambda)\tilde{\sigma}^2(0)\}$ as the average $-n^{-1} \sum_{i=1}^n \partial\boldsymbol{\psi}^{(B)}\{\mathbf{Q}_i^{(B)}; \boldsymbol{\Omega}\}/\partial\boldsymbol{\Omega}^T$ evaluated at $\boldsymbol{\Omega} = \{\tilde{\boldsymbol{\Omega}}_{-\sigma^2}(0)^T, (1 + \lambda)\tilde{\sigma}^2(0)\}^T$.

(I) An estimator for the variance-covariance matrix of $\mathbf{T}_1(\lambda)$, $\hat{\boldsymbol{\nu}}_1$:

Using the influence function approximation, we have

$$n^{1/2} \left\{ \tilde{\boldsymbol{\Omega}}(\lambda) - \boldsymbol{\Omega}(\lambda) \right\} = n^{-1/2} \sum_{i=1}^n \mathbf{A}_2^{-1} \left\{ \boldsymbol{\Omega}(\lambda) \right\} \boldsymbol{\psi}^{(B)} \left\{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}(\lambda) \right\} + \boldsymbol{o}_p(1), \quad (\text{B.1})$$

$$n^{1/2} \left\{ \tilde{\boldsymbol{\Omega}}(0) - \boldsymbol{\Omega}(0) \right\} = n^{-1/2} \sum_{i=1}^n \mathbf{A}_1^{-1} \left\{ \boldsymbol{\Omega}(0) \right\} \boldsymbol{\psi} \left\{ \mathbf{Q}_i; \boldsymbol{\Omega}(0) \right\} + \boldsymbol{o}_p(1). \quad (\text{B.2})$$

Subtracting (B.2) from (B.1) yields

$$\begin{aligned} \mathbf{T}_1(\lambda) &= n^{1/2} \left\{ \boldsymbol{\Omega}(\lambda) - \boldsymbol{\Omega}(0) \right\} + \\ &\quad n^{-1/2} \sum_{i=1}^n \left[\mathbf{A}_2^{-1} \left\{ \boldsymbol{\Omega}(\lambda) \right\} \boldsymbol{\psi}^{(B)} \left\{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}(\lambda) - \mathbf{A}_1^{-1} \left\{ \boldsymbol{\Omega}(0) \right\} \boldsymbol{\psi} \left\{ \mathbf{Q}_i; \boldsymbol{\Omega}(0) \right\} \right] + \boldsymbol{o}_p(1) \\ &= n^{1/2} \left\{ \boldsymbol{\Omega}(\lambda) - \boldsymbol{\Omega}(0) \right\} + n^{-1/2} \sum_{i=1}^n \mathbf{R}_{1i}^* + \boldsymbol{o}_p(1), \end{aligned} \quad (\text{B.3})$$

where

$$\mathbf{R}_{1i}^* = \mathbf{A}_2^{-1} \left\{ \boldsymbol{\Omega}(\lambda) \right\} \boldsymbol{\psi}^{(B)} \left\{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}(\lambda) \right\} - \mathbf{A}_1^{-1} \left\{ \boldsymbol{\Omega}(0) \right\} \boldsymbol{\psi} \left\{ \mathbf{Q}_i; \boldsymbol{\Omega}(0) \right\}. \quad (\text{B.4})$$

Based on the approximation in (B.3), an estimator for the variance-covariance matrix of \mathbf{T}_1 is given by

$$\hat{\boldsymbol{\nu}}_1 = (n-1)^{-1} \sum_{i=1}^n (\mathbf{R}_{1i} - \bar{\mathbf{R}}_1)(\mathbf{R}_{1i} - \bar{\mathbf{R}}_1)^T,$$

where $\bar{\mathbf{R}}_1 = n^{-1} \sum_{i=1}^n \mathbf{R}_{1i}$, and

$$\mathbf{R}_{1i} = \hat{\mathbf{A}}_2^{-1} \left\{ \mathbf{Q}^{(B)}; \tilde{\boldsymbol{\Omega}}(\lambda) \right\} \boldsymbol{\psi}^{(B)} \left\{ \mathbf{Q}_i^{(B)}(\lambda); \tilde{\boldsymbol{\Omega}}(\lambda) \right\} - \hat{\mathbf{A}}_1^{-1} \left\{ \mathbf{Q}; \tilde{\boldsymbol{\Omega}}(0) \right\} \boldsymbol{\psi} \left\{ \mathbf{Q}_i; \tilde{\boldsymbol{\Omega}}(0) \right\}.$$

(II) An estimator for the variance-covariance matrix of $\mathbf{T}_2(\lambda)$, $\widehat{\boldsymbol{\nu}}_2$:

The first-order Taylor expansion of $\mathbf{T}_2(\lambda)$ around $\boldsymbol{\Omega}(0)$ gives the following approximation,

$$\begin{aligned} \mathbf{T}_2(\lambda) &\approx n^{-1/2} \sum_{i=1}^n \boldsymbol{\psi}^{(B)} \left\{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}_{-\sigma^2}(0), (1+\lambda)\sigma^2(0) \right\} + \\ &\quad n^{-1/2} \sum_{i=1}^n \frac{\partial \boldsymbol{\psi}^{(B)} \left\{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega} \right\}}{\partial \boldsymbol{\Omega}^T} \Big|_{\boldsymbol{\Omega} = \left\{ \boldsymbol{\Omega}_{-\sigma^2}(0)^T, (1+\lambda)\sigma^2(0) \right\}^T} \left\{ \widetilde{\boldsymbol{\Omega}}(0) - \boldsymbol{\Omega}(0) \right\} \\ &\approx n^{-1/2} \sum_{i=1}^n \boldsymbol{\psi}^{(B)} \left\{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}_{-\sigma^2}(0), (1+\lambda)\sigma^2(0) \right\} - \\ &\quad \mathbf{A}_2 \left\{ \boldsymbol{\Omega}_{-\sigma^2}(0), (1+\lambda)\sigma^2(0) \right\} n^{-1/2} \sum_{i=1}^n \mathbf{A}_1^{-1} \left\{ \boldsymbol{\Omega}(0) \right\} \boldsymbol{\psi} \left\{ \mathbf{Q}_i; \boldsymbol{\Omega}(0) \right\} \end{aligned} \quad (\text{B.5})$$

$$\begin{aligned} &= n^{-1/2} \sum_{i=1}^n \left[\boldsymbol{\psi}^{(B)} \left\{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}_{-\sigma^2}(0), (1+\lambda)\sigma^2(0) \right\} \right. \\ &\quad \left. - \mathbf{A}_2 \left\{ \boldsymbol{\Omega}_{-\sigma^2}(0), (1+\lambda)\sigma^2(0) \right\} \mathbf{A}_1^{-1} \left\{ \boldsymbol{\Omega}(0) \right\} \boldsymbol{\psi} \left\{ \mathbf{Q}_i; \boldsymbol{\Omega}(0) \right\} \right] \\ &= n^{-1/2} \sum_{i=1}^n \mathbf{R}_{2i}^*, \end{aligned} \quad (\text{B.6})$$

where

$$\mathbf{R}_{2i}^* = \boldsymbol{\psi}^{(B)} \left\{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}_{-\sigma^2}(0), (1+\lambda)\sigma^2(0) \right\} - \mathbf{A}_2 \left\{ \boldsymbol{\Omega}_{-\sigma^2}(0), (1+\lambda)\sigma^2(0) \right\} \mathbf{A}_1^{-1} \left\{ \boldsymbol{\Omega}(0) \right\} \boldsymbol{\psi} \left\{ \mathbf{Q}_i; \boldsymbol{\Omega}(0) \right\}. \quad (\text{B.7})$$

The approximation in (B.5) follows from (B.2) and that, as $n \rightarrow \infty$,

$$n^{-1} \sum_{i=1}^n \frac{\partial \boldsymbol{\psi}^{(B)} \left\{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega} \right\}}{\partial \boldsymbol{\Omega}^T} \Big|_{\boldsymbol{\Omega} = \left\{ \boldsymbol{\Omega}_{-\sigma^2}(0)^T, (1+\lambda)\sigma^2(0) \right\}^T} \xrightarrow{p} \mathbf{A}_2 \left\{ \boldsymbol{\Omega}_{-\sigma^2}(0), (1+\lambda)\sigma^2(0) \right\}.$$

Based on the approximation in (B.6), an estimator for the asymptotic variance-covariance matrix of $\mathbf{T}_2(\lambda)$ is given by

$$\widehat{\boldsymbol{\nu}}_2 = (n-1)^{-1} \sum_{i=1}^n (\mathbf{R}_{2i} - \overline{\mathbf{R}}_2)(\mathbf{R}_{2i} - \overline{\mathbf{R}}_2)^T,$$

where $\overline{\mathbf{R}}_2 = n^{-1} \sum_{i=1}^n \mathbf{R}_{2i}$ and

$$\mathbf{R}_{2i} = \boldsymbol{\psi}^{(B)} \left\{ \mathbf{Q}_i^{(B)}(\lambda); \widetilde{\boldsymbol{\Omega}}_{-\sigma^2}(0), (1+\lambda)\tilde{\sigma}^2(0) \right\} - \widehat{\mathbf{A}}_2 \left\{ \widetilde{\boldsymbol{\Omega}}_{-\sigma^2}(0), (1+\lambda)\tilde{\sigma}^2(0) \right\} \widehat{\mathbf{A}}_1^{-1} \left\{ \widetilde{\boldsymbol{\Omega}}(0) \right\} \boldsymbol{\psi} \left\{ \mathbf{Q}_i; \widetilde{\boldsymbol{\Omega}}(0) \right\}.$$

Web Appendix C: Asymptotic Equivalence Between $\mathbf{T}_1^*(\lambda)$ and $\mathbf{T}_2^*(\lambda)$

First consider the first-order Taylor expansion of $\mathbf{T}_2(\lambda)$ around $\boldsymbol{\Omega}(\lambda)$ under H_a ,

$$\begin{aligned}
\mathbf{T}_2(\lambda) &= n^{-1/2} \sum_{i=1}^n \boldsymbol{\psi}^{(B)} \{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}(\lambda) \} + \\
&\quad n^{-1/2} \sum_{i=1}^n \frac{\partial \boldsymbol{\psi}^{(B)} \{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega} \}}{\partial \boldsymbol{\Omega}^T} \Big|_{\boldsymbol{\Omega} = \boldsymbol{\Omega}(\lambda)} \left\{ \tilde{\boldsymbol{\Omega}}(0) - \boldsymbol{\Omega}(0) - n^{-1/2} \boldsymbol{\Delta}^*(\lambda) \right\} + \mathbf{o}_p(1) \\
&= n^{-1/2} \sum_{i=1}^n \boldsymbol{\psi}^{(B)} \{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}(\lambda) \} - \mathbf{A}_2 \{ \boldsymbol{\Omega}(\lambda) \} \mathbf{A}_1^{-1} \{ \boldsymbol{\Omega}(0) \} n^{-1/2} \sum_{i=1}^n \boldsymbol{\psi} \{ \mathbf{Q}_i; \boldsymbol{\Omega}(0) \} \\
&\quad + \mathbf{A}_2 \{ \boldsymbol{\Omega}(\lambda) \} \boldsymbol{\Delta}^*(\lambda) + \mathbf{o}_p(1) \\
&= \mathbf{A}_2 \{ \boldsymbol{\Omega}(\lambda) \} \boldsymbol{\Delta}^*(\lambda) + \\
&\quad n^{-1/2} \sum_{i=1}^n \left[\boldsymbol{\psi}^{(B)} \{ \mathbf{Q}_i^{(B)}(\lambda); \boldsymbol{\Omega}(\lambda) \} - \mathbf{A}_2 \{ \boldsymbol{\Omega}(\lambda) \} \mathbf{A}_1^{-1} \{ \boldsymbol{\Omega}(0) \} \boldsymbol{\psi} \{ \mathbf{Q}_i; \boldsymbol{\Omega}(0) \} \right] + \mathbf{o}_p(1) \\
&= \mathbf{A}_2 \{ \boldsymbol{\Omega}(\lambda) \} \boldsymbol{\Delta}^*(\lambda) + \mathbf{A}_2 \{ \boldsymbol{\Omega}(\lambda) \} n^{-1/2} \sum_{i=1}^n \mathbf{R}_{1i}^* + \mathbf{o}_p(1). \tag{C.1}
\end{aligned}$$

From (B.3), under H_a , $\mathbf{T}_1(\lambda) = \boldsymbol{\Delta}^*(\lambda) + n^{-1/2} \sum_{i=1}^n \mathbf{R}_{1i}^* + \mathbf{o}_p(1)$. Therefore, (C.1) implies

$$\mathbf{T}_2(\lambda) = \mathbf{A}_2 \{ \boldsymbol{\Omega}(\lambda) \} \mathbf{T}_1(\lambda) + \mathbf{o}_p(1). \tag{C.2}$$

Next relate $\text{var}(\mathbf{R}_{2i}^*)$ and $\text{var}(\mathbf{R}_{1i}^*)$ under H_a as $n \rightarrow \infty$. By (B.7),

$$\begin{aligned}
\mathbf{R}_{2i}^* &= \mathbf{A}_2 \{ \boldsymbol{\Omega}_{-\sigma^2}(0), \sigma^2(\lambda) \} \left[\mathbf{A}_2^{-1} \{ \boldsymbol{\Omega}_{-\sigma^2}(0), \sigma^2(\lambda) \} \boldsymbol{\psi}^{(B)} \{ \mathbf{Q}_i^{(B)}; \boldsymbol{\Omega}_{-\sigma^2}(0), \sigma^2(\lambda) \} - \right. \\
&\quad \left. \mathbf{A}_1^{-1} \{ \boldsymbol{\Omega}(0) \} \boldsymbol{\psi} \{ \mathbf{Q}_i; \boldsymbol{\Omega}(0) \} \right]. \\
&\longrightarrow \mathbf{A}_2 \{ \boldsymbol{\Omega}(\lambda) \} \left[\mathbf{A}_2^{-1} \{ \boldsymbol{\Omega}(\lambda) \} \boldsymbol{\psi}^{(B)} \{ \mathbf{Q}_i^{(B)}; \boldsymbol{\Omega}(\lambda) \} - \mathbf{A}_1^{-1} \{ \boldsymbol{\Omega}(0) \} \boldsymbol{\psi} \{ \mathbf{Q}_i; \boldsymbol{\Omega}(0) \} \right] \\
&= \mathbf{A}_2 \{ \boldsymbol{\Omega}(\lambda) \} \mathbf{R}_{1i}^*.
\end{aligned}$$

Therefore, under H_a , as $n \rightarrow \infty$, $\text{var}(\mathbf{R}_{2i}^*) \rightarrow \mathbf{A}_2 \{ \boldsymbol{\Omega}(\lambda) \} \text{var}(\mathbf{R}_{1i}^*) \mathbf{A}_2^T \{ \boldsymbol{\Omega}(\lambda) \}$, thus

$$\text{var}(\mathbf{R}_{2i}^*)^{-1} \rightarrow \mathbf{A}_2^{-1} \{ \boldsymbol{\Omega}(\lambda) \}^T \text{var}(\mathbf{R}_{1i}^*)^{-1} \mathbf{A}_2^{-1} \{ \boldsymbol{\Omega}(\lambda) \}. \tag{C.3}$$

Lastly, by the definition of $\mathbf{T}_2^*(\lambda)$ and (C.2),

$$\begin{aligned}
\mathbf{T}_2^{*T}(\lambda)\mathbf{T}_2^*(\lambda) &= \mathbf{T}_2^T(\lambda)\text{var}(\mathbf{R}_{2i}^*)^{-1}\mathbf{T}_2(\lambda) \\
&= \mathbf{T}_1^T(\lambda)\mathbf{A}_2^T\{\boldsymbol{\Omega}(\lambda)\}\text{var}(\mathbf{R}_{2i}^*)^{-1}\mathbf{A}_2^T\{\boldsymbol{\Omega}(\lambda)\}\mathbf{T}_1(\lambda) + \boldsymbol{o}_p(1) \\
\left[\text{by (C.3)} \right] &\longrightarrow \mathbf{T}_1^T(\lambda)\text{var}(\mathbf{R}_{1i}^*)^{-1}\mathbf{T}_1(\lambda) \\
&= \mathbf{T}_1^{*T}(\lambda)\mathbf{T}_1^*(\lambda),
\end{aligned}$$

which establishes the asymptotic equivalence between $\mathbf{T}_1^*(\lambda)$ and $\mathbf{T}_2^*(\lambda)$.

Web Appendix D: SIMEX Plots for the SWAN Data

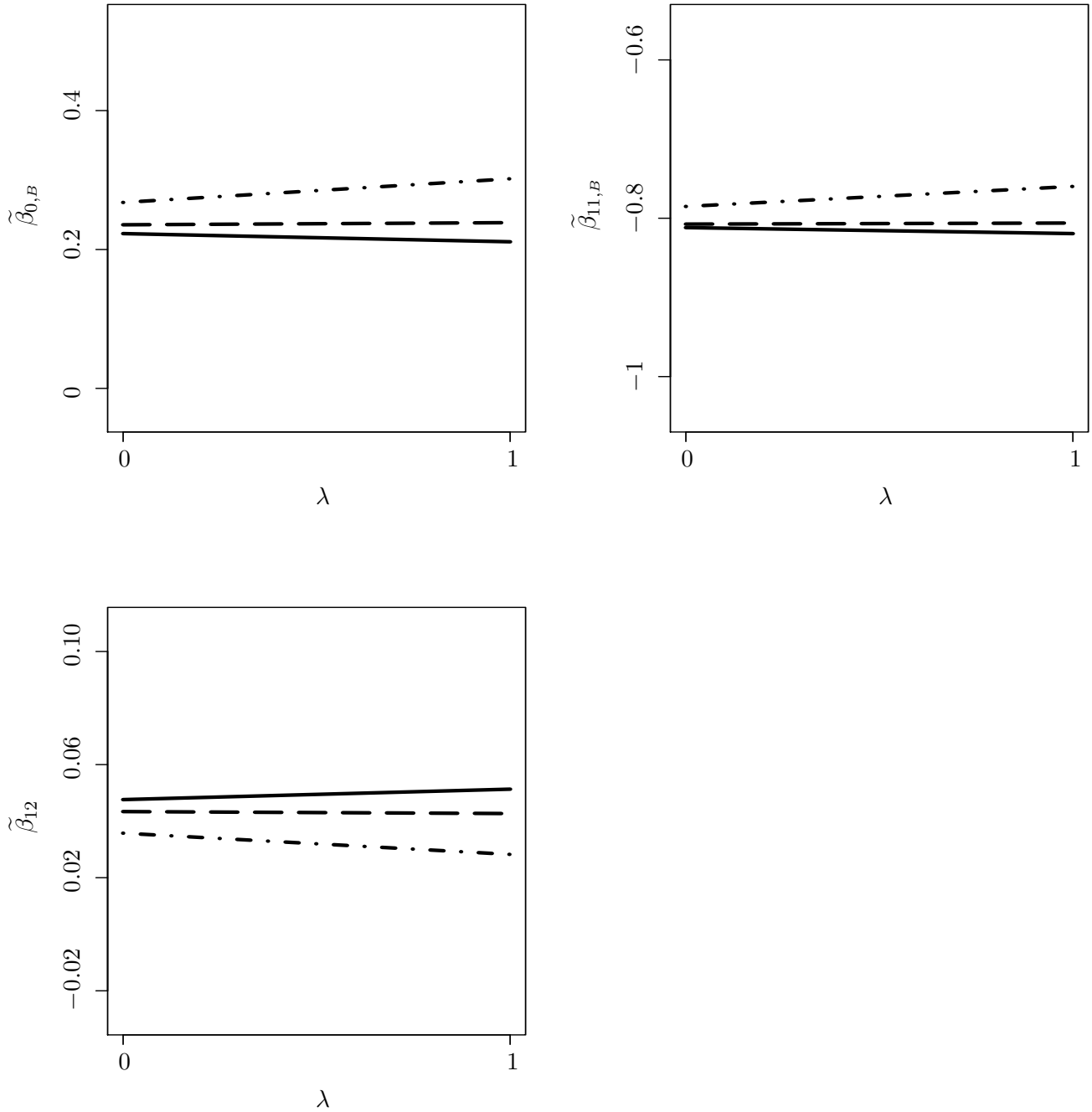


Figure 1. SIMEX plots of the MLEs $\tilde{\theta}_B^{(c)}(\lambda)$, $\tilde{\theta}_B^{(m)}(\lambda)$, and $\tilde{\theta}_B^{(n)}(\lambda)$ computed from the SWAN data. The line types are, $\tilde{\theta}_B^{(c)}(\lambda)$: long dashed; $\tilde{\theta}_B^{(m)}(\lambda)$: dash-dotted; and $\tilde{\theta}_B^{(n)}(\lambda)$: solid. The ranges of the vertical axes are set to be one estimated standard deviation of $\tilde{\theta}_B^{(n)}(0)$ below and above the average of the three types of estimates at $\lambda = 0$.